



# Leaving undesirable partners

*- A sufficient condition to explain the evolutionary emergence of cooperation*

**Luis R. Izquierdo**

University of Burgos (Spain)

**Segismundo S. Izquierdo**

University of Valladolid (Spain)

**Fernando Vega-Redondo**

European University Institute (Italy)

Paper: <http://dx.doi.org/10.1016/j.jedc.2014.06.007>

Online model: <http://luis.izqui.org/models/LeLeLe/index.html>

5-minute video: [http://luis.izqui.org/papers/Izquierdo\\_Izquierdo\\_Vega-Redondo\\_2014.html](http://luis.izqui.org/papers/Izquierdo_Izquierdo_Vega-Redondo_2014.html)

# Outline

---

- Introduction
- The question and the approach
- The model
- Simulation results
- A mean-dynamics approximation
- A closed-form solution
- Conclusions



# Introduction

---

How did cooperative behaviour evolve?



# Social Dilemmas

## The Prisoner's Dilemma

Pris. Dil.:  $T > R > P > S$

↓ Player 2

		Player 2	
		Cooperate	Defect
Player 1	Cooperate	3, 3	0, 4
	Defect	4, 0	1, 1



# Social Dilemmas

## The Prisoner's Dilemma

Cooperation is mutually beneficial, but very fragile.

Pris. Dil.:  $T > R > P > S$

Player 2

Player 1

	Cooperate	Defect
Cooperate	3, 3	0, 4
Defect	4, 0	1, 1



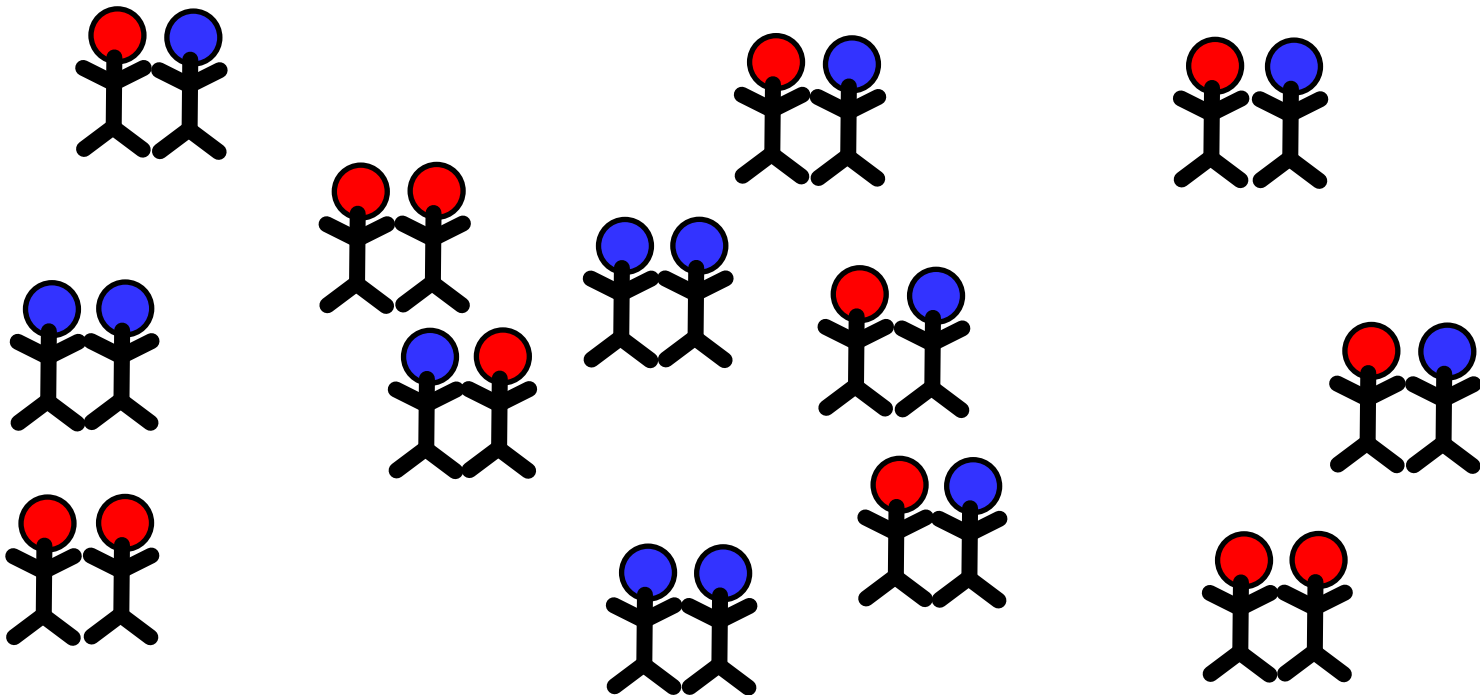
# Positive assortment

Processes or conditions that allow cooperators to preferentially interact among themselves.

## Expected Payoff:

Pris. Dil.:  $T > R > P > S$

$x_C$  : probability of interacting with a cooperator  
 $x_D$  : probability of interacting with a defector  
( $1 - x_C$ )



# Positive assortment

Processes or conditions that allow cooperators to preferentially interact among themselves.

## Expected Payoff:

Pris. Dil.:  $T > R > P > S$

$x_C$ : probability of interacting with a cooperator  
 $x_D$ : probability of interacting with a defector  
 $(1 - x_C)$

For Cooperators:  $\hat{R} x_C + \hat{S} (1 - x_C)$

For Defectors:  $\hat{T} x_C + \hat{P} (1 - x_C)$

For Cooperators:  $\hat{R} x_{C|C} + \hat{S} (1 - x_{C|C})$

For Defectors:  $\hat{T} x_{C|D} + \hat{P} (1 - x_{C|D})$

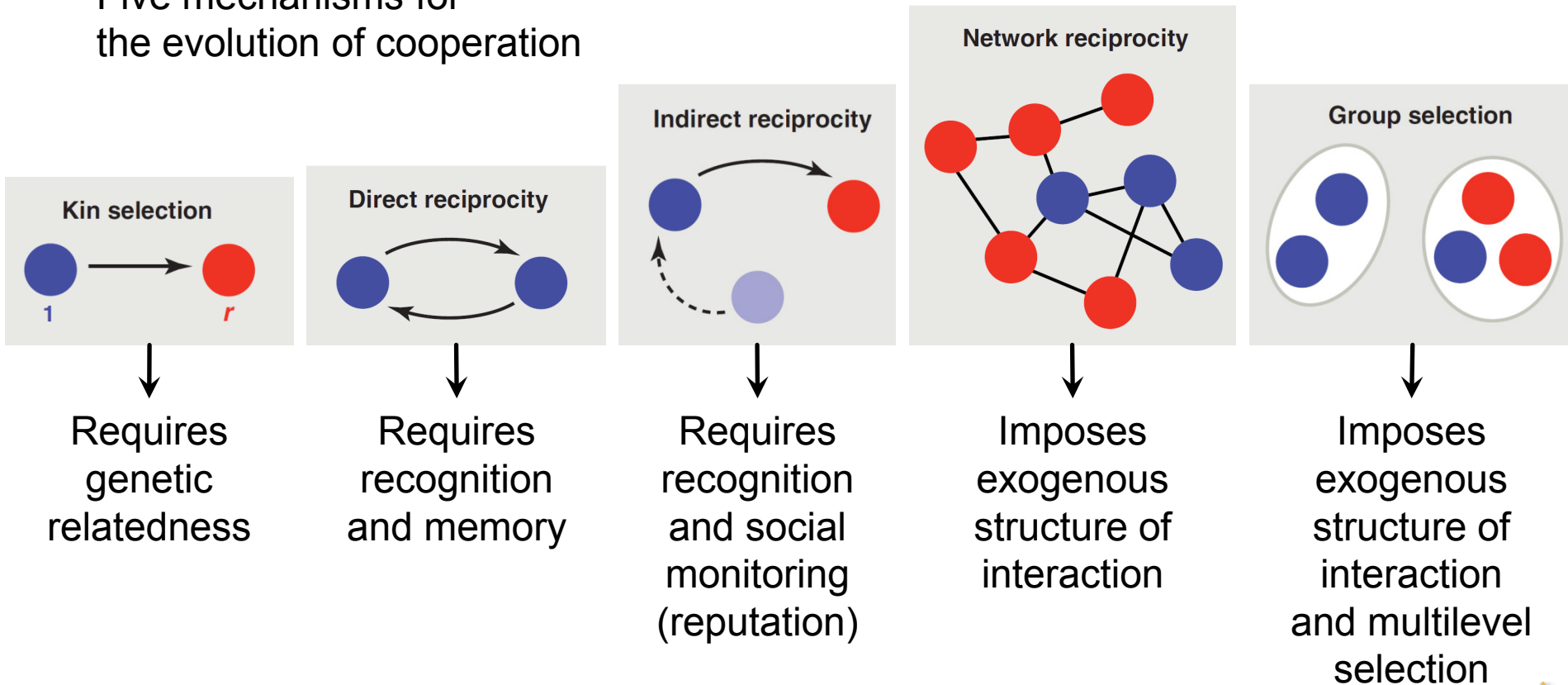
**The probability of interacting with a cooperator must be greater for a cooperator than for a defector**



# Introduction

## How did cooperative behaviour evolve?

Five mechanisms for the evolution of cooperation



● Cooperators ● Defectors

Nowak, M. A. (2006) Five rules for the evolution of cooperation. *Science* 314, 1560-1563.



# Introduction

---

## Interested in **conditional assortment**

Situations where individuals can influence with whom they interact (or not), or at least for how long they do it.

- *Pre-interaction* partner selection (or refusal)
  - Requires advanced cognitive abilities.
  - E.g.: Indirect reciprocity (reputation), external signals or tags...
- *Post-interaction* partner refusal  
**(conditional dissociation)**
  - It does not require memory or the ability to anticipate the behaviour of new partners.
  - It only requires the capacity to escape an unpleasant situation.



# Outline

---

- Introduction
- The question and the approach
- The model
- Simulation results
- A mean-dynamics approximation
- A closed-form solution
- Conclusions



# The question and the approach

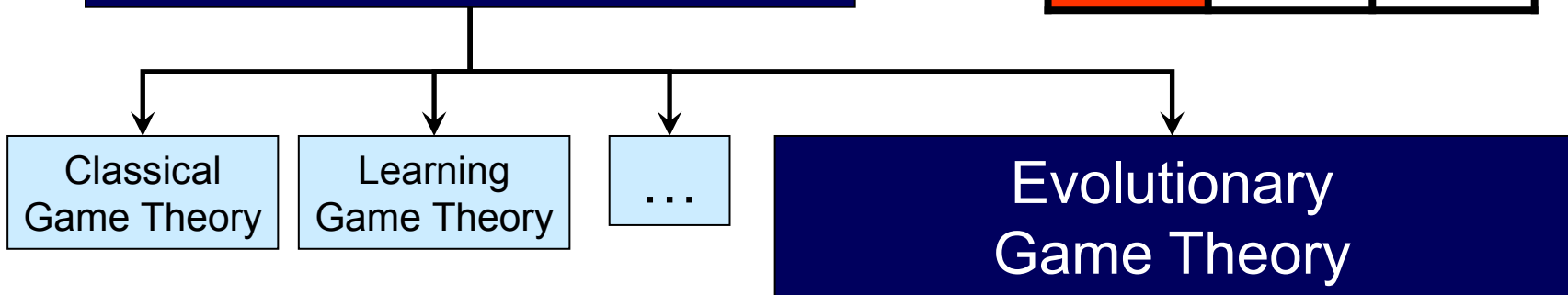
---

- Can a simple mechanism of **conditional dissociation** explain, **only by itself**, the evolutionary emergence and stability of cooperation among unrelated individuals?
- **The simplest model we can think of**, to study the effect of conditional dissociation isolated from other mechanisms.
- **Unbiased selection of strategies**  
All individuals in the population share a common capability to gather information and to condition their actions on that information, and then allow for *every possible strategy within such a uniform setup*.
- **Beyond the identification of “winning” strategies**  
Also concerned with the issue of whether some well-defined *pattern of aggregate behaviour* eventually emerges.  
(Even under perpetual turnover in strategy choice.)



# The approach

## Game Theory as a Framework



		Player 2	
		Cooperate	Defect
Player 1	Cooperate	3, 3	0, 4
	Defect	4, 0	1, 1

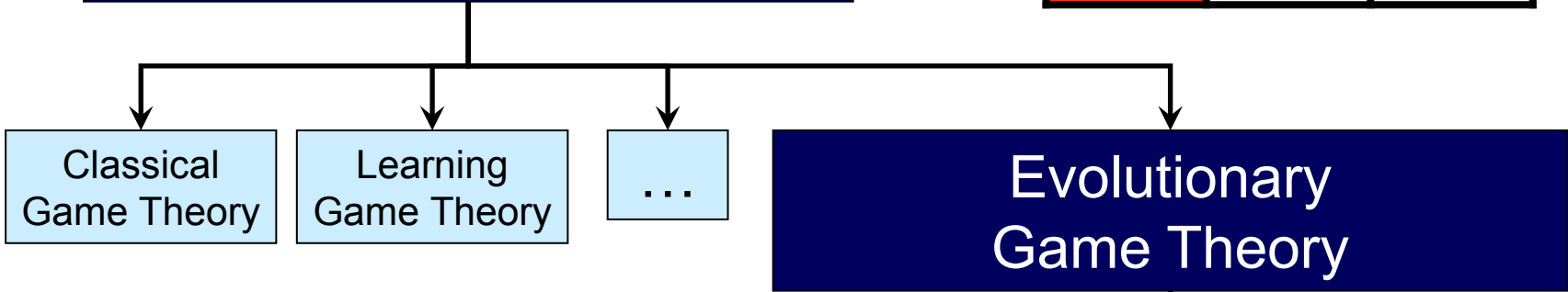
- **Dynamic process, where entities which are *more successful* at a particular time will have the best chance of being present in the future.**



# The approach

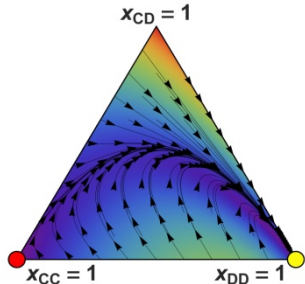
## Game Theory as a Framework

		Player 2	
		Cooperate	Defect
Player 1	Cooperate	3, 3	0, 4
	Defect	4, 0	1, 1

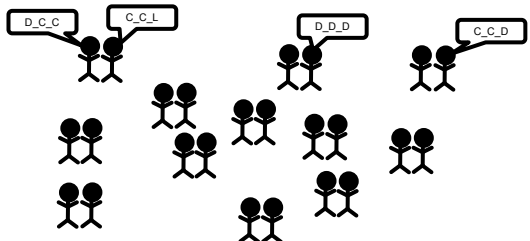


### Mainstream Evolutionary Game Theory

- Infinite populations
- Random Pairings
- Proportional Fitness Rule
- Arbitrarily small mutations
- No random drift



### Explicit modelling of actual populations



# Outline

---

- Introduction
- The question and the approach
- The model
- Simulation results
- A mean-dynamics approximation
- A closed-form solution
- Conclusions



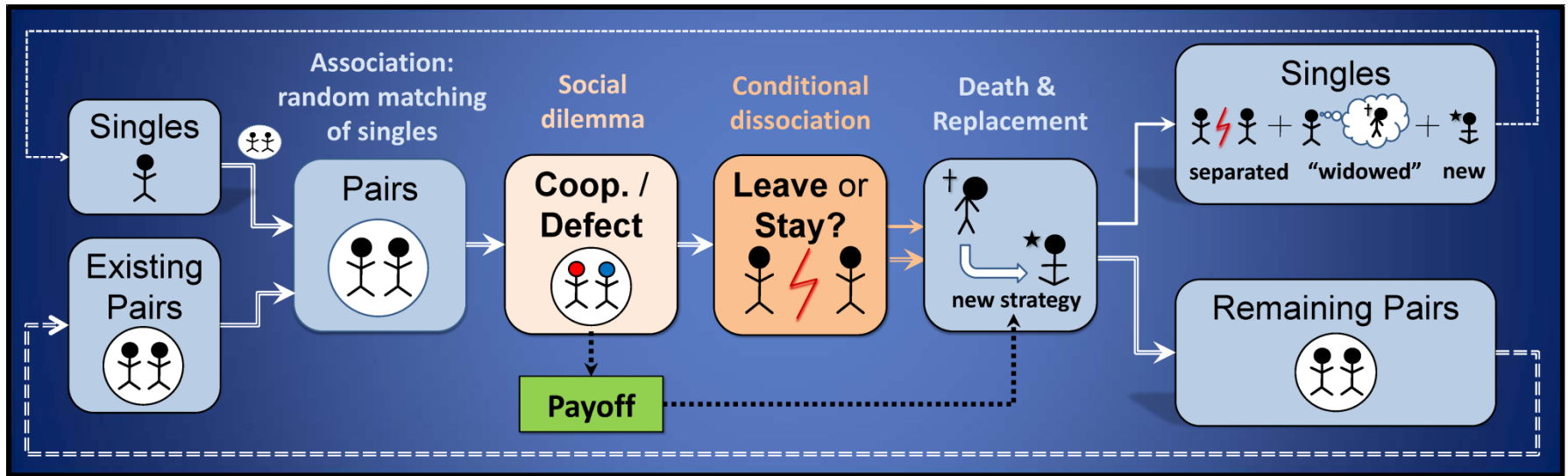
# The game (Prisoner's Dilemma)

The Prisoner's Dilemma:  
Payoffs

		Player 2	
		Cooperate	Defect
Player 1	Cooperate	3, 3	0, 4
	Defect	4, 0	1, 1



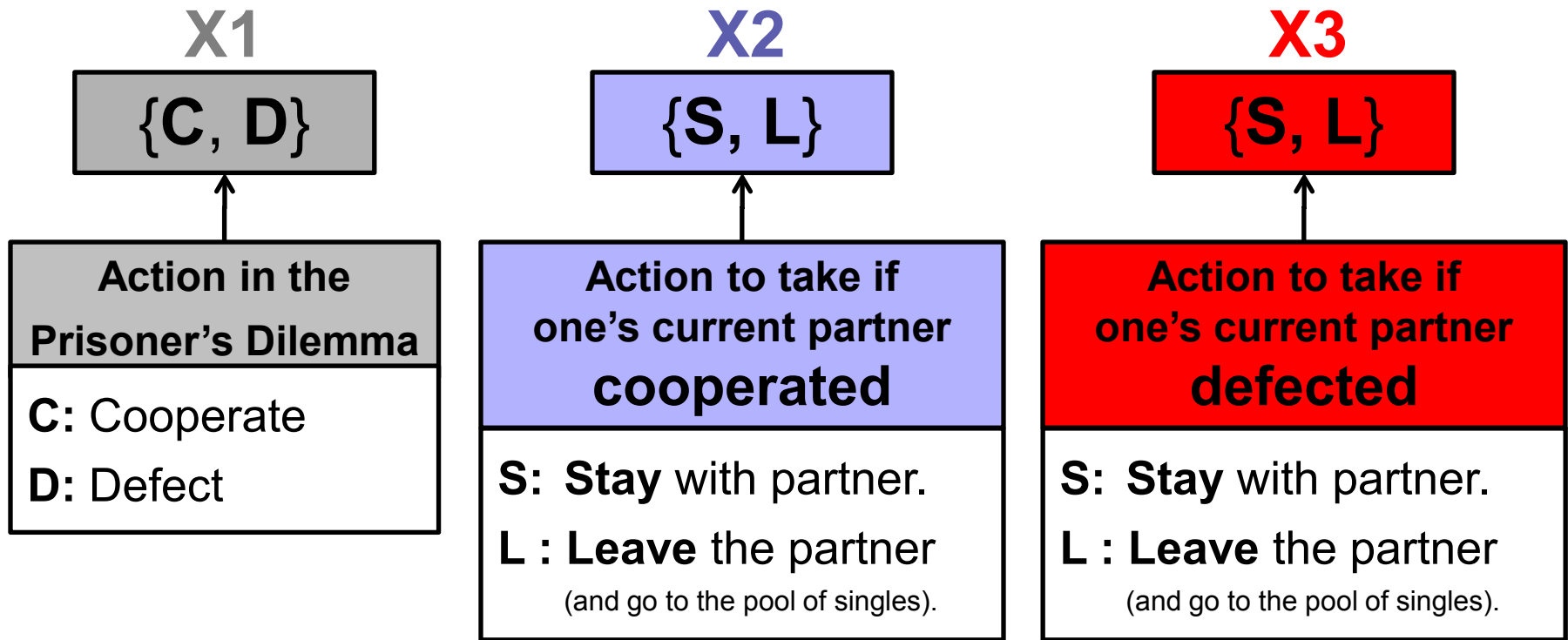
# The timeline



Sequence of events within each time period



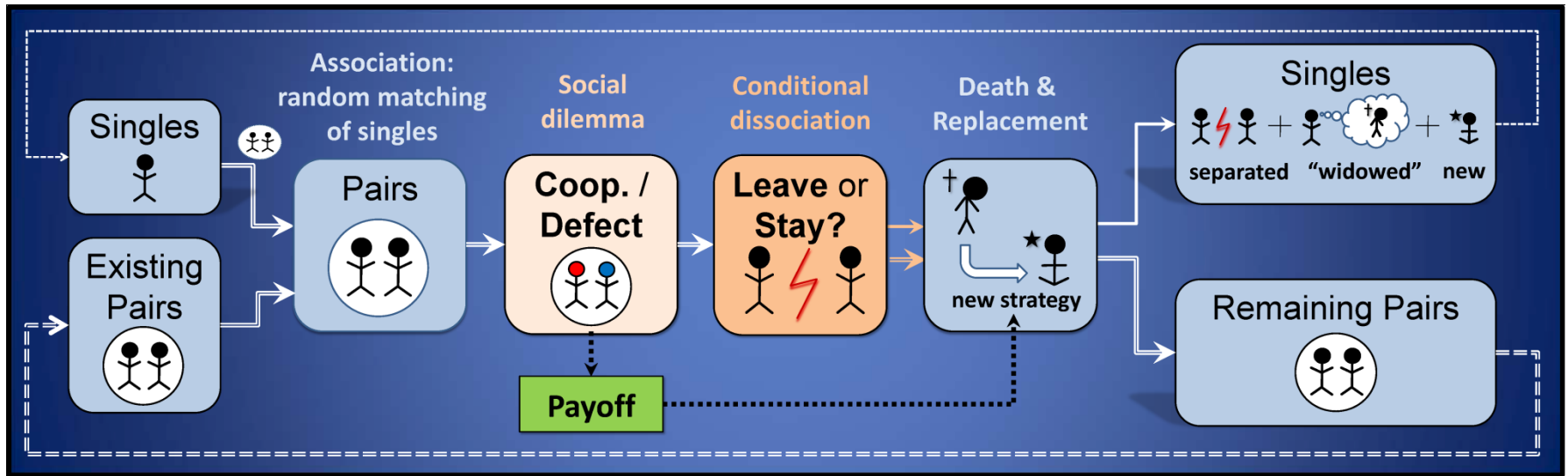
# The strategies: X1\_X2\_X3



Cooperate and leave after a partner's defection: C\_S\_L  
(Conditional dissociator or Out-for-Tat)



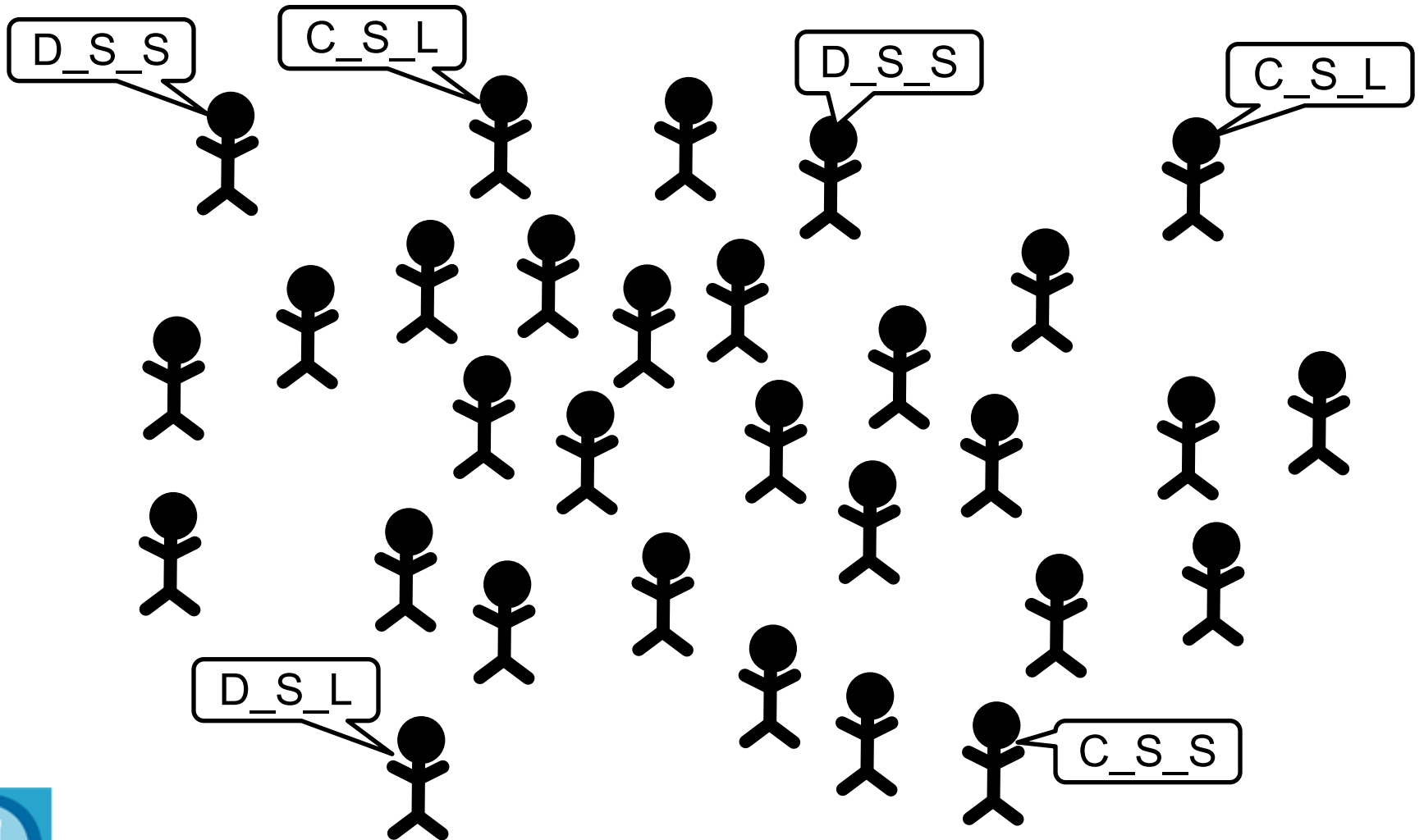
# The timeline



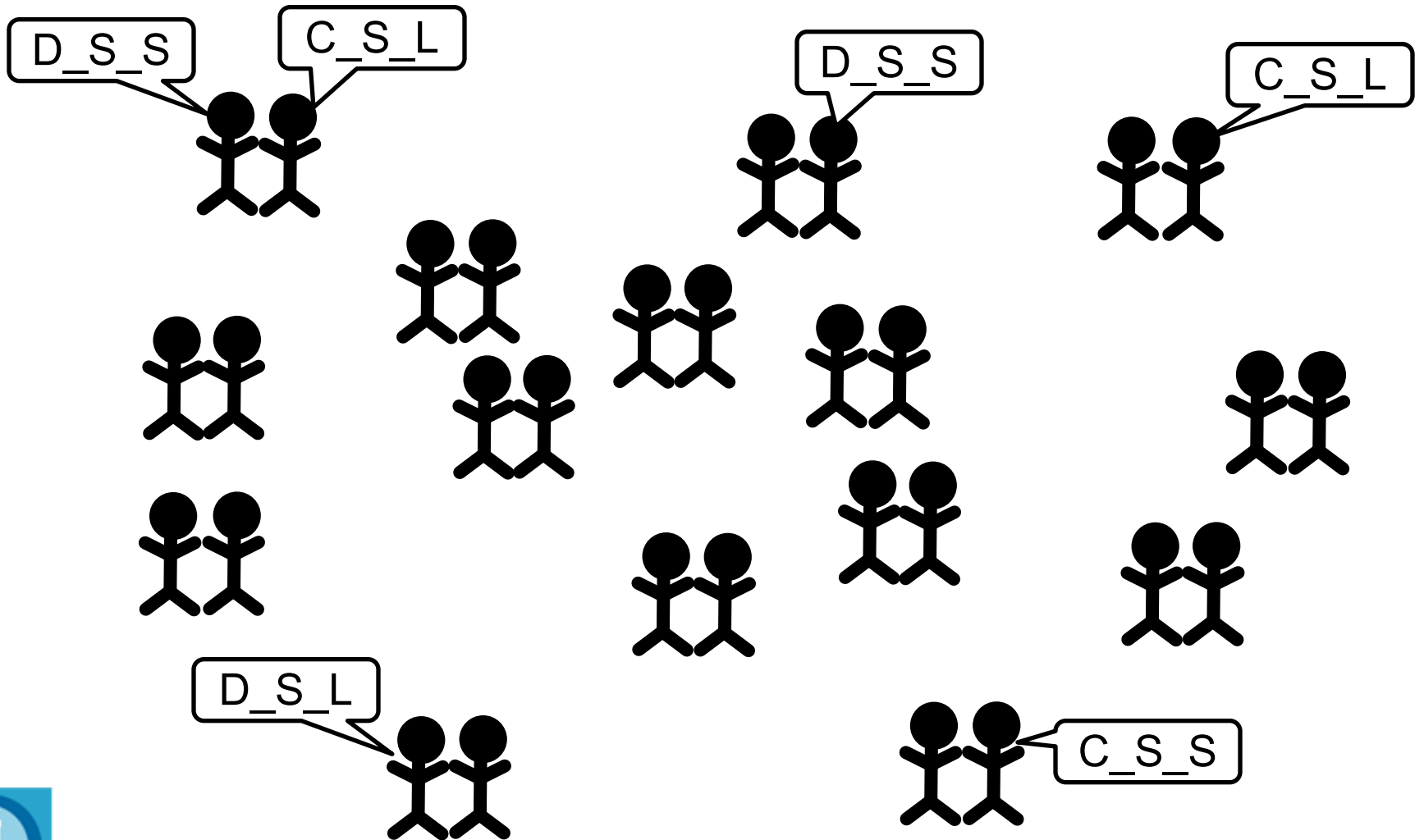
Sequence of events within each time period



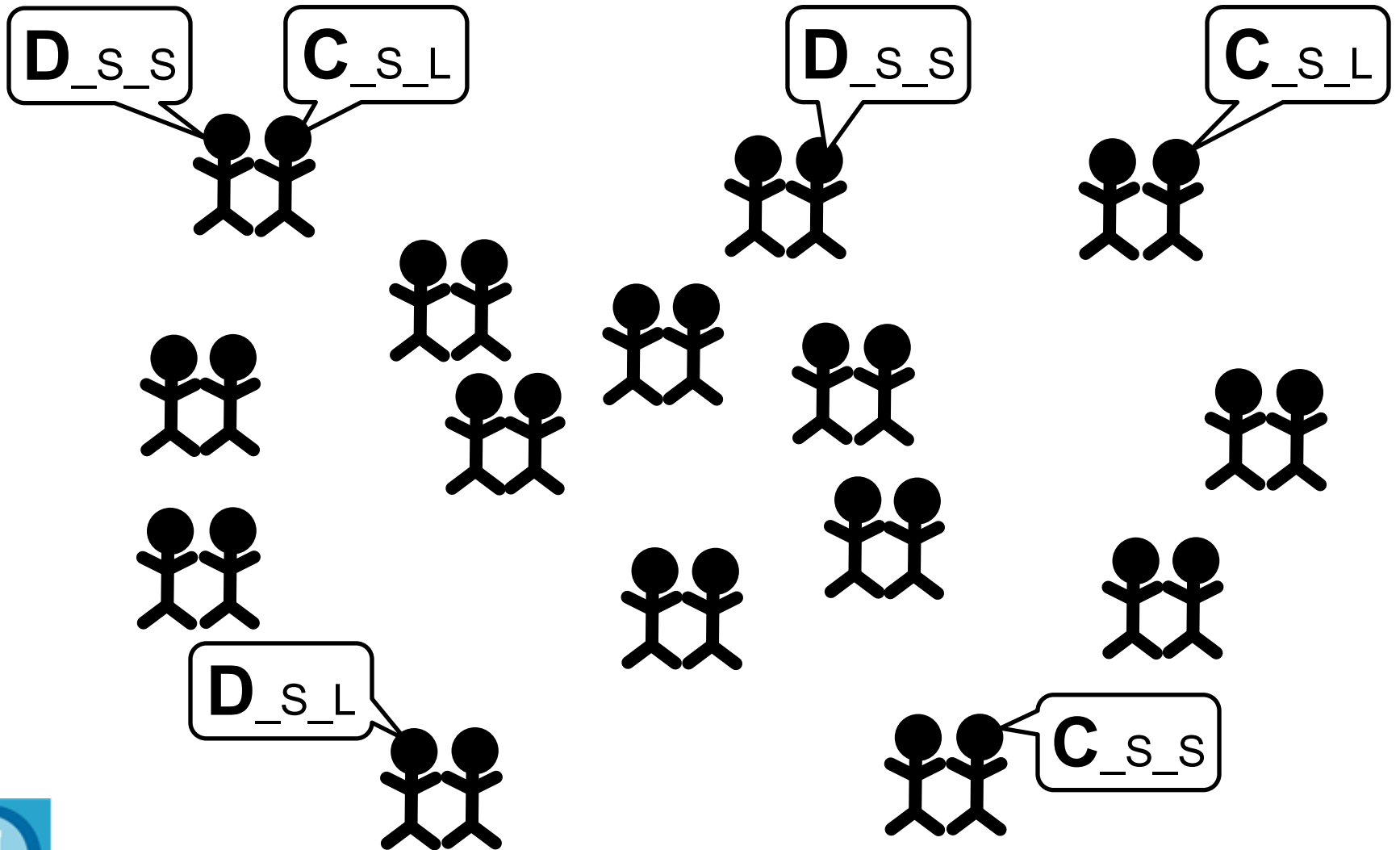
# The initial population



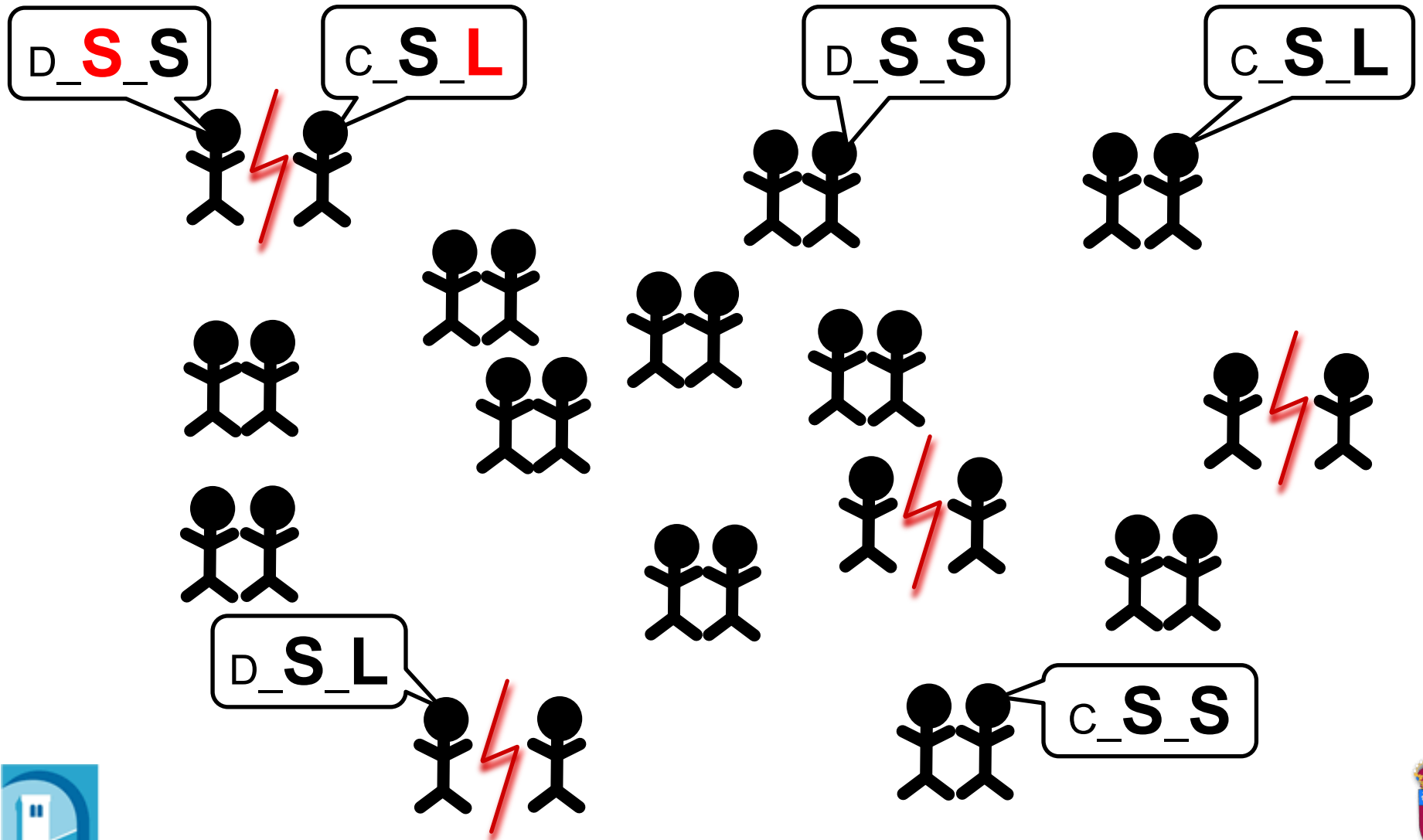
# The random pairing of singles



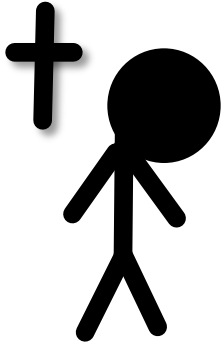
# The Prisoner's Dilemma game



# Should I stay or should I go?



# Death and Replacement



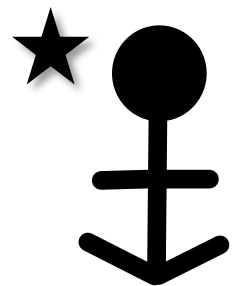
Individuals randomly die, an event that occurs independently for each individual with probability  $p$  in each time period.

Hence, the lifespan of an individual is geometrically distributed with mean-value **expLife** =  $1/p$ .

Each dead individual is immediately replaced by a new entrant

The probability of adopting a certain strategy is proportional to its aggregate payoff.

(Reproduction is proportional to payoffs and population size is kept constant.)

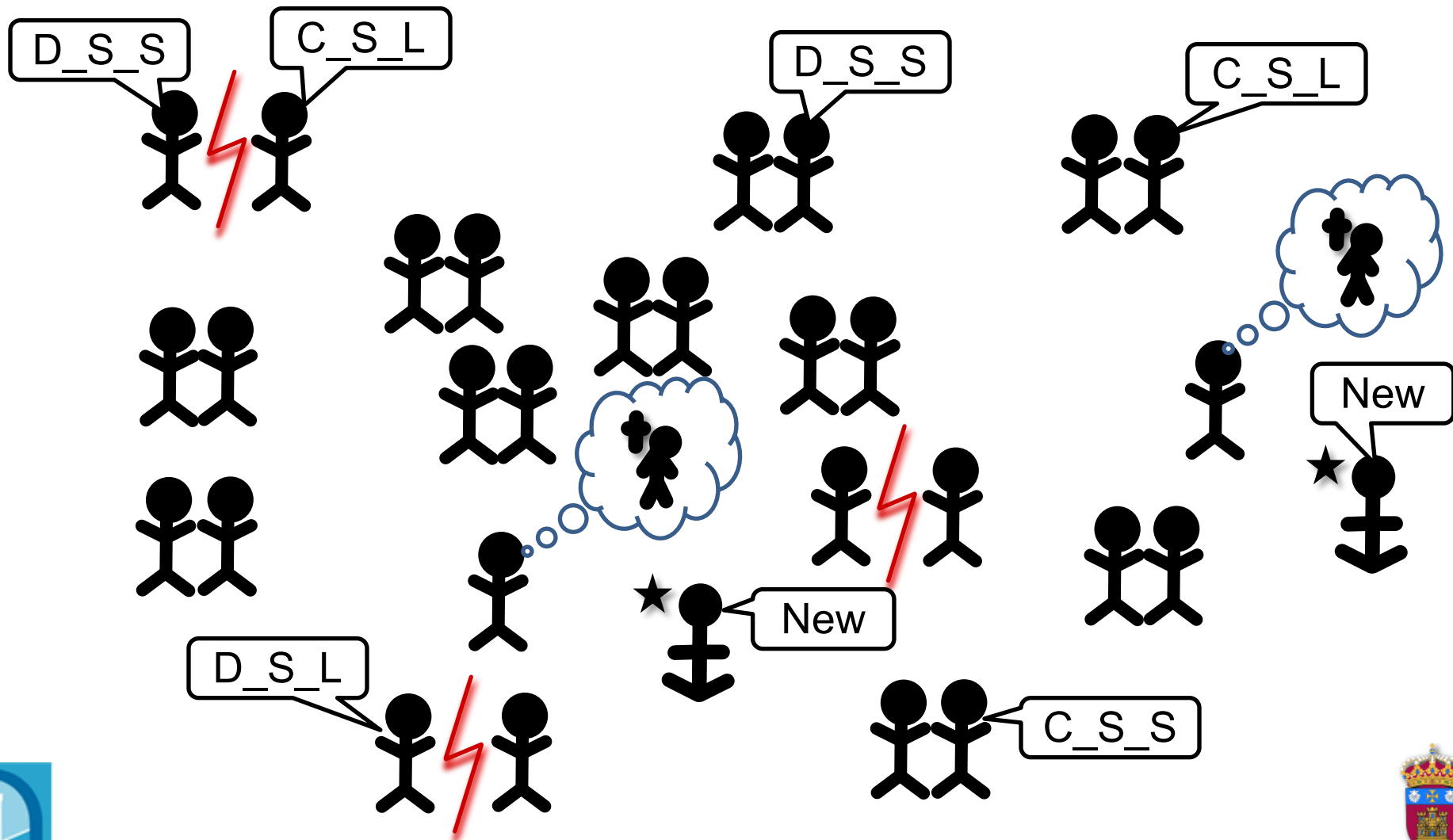


**new strategy**

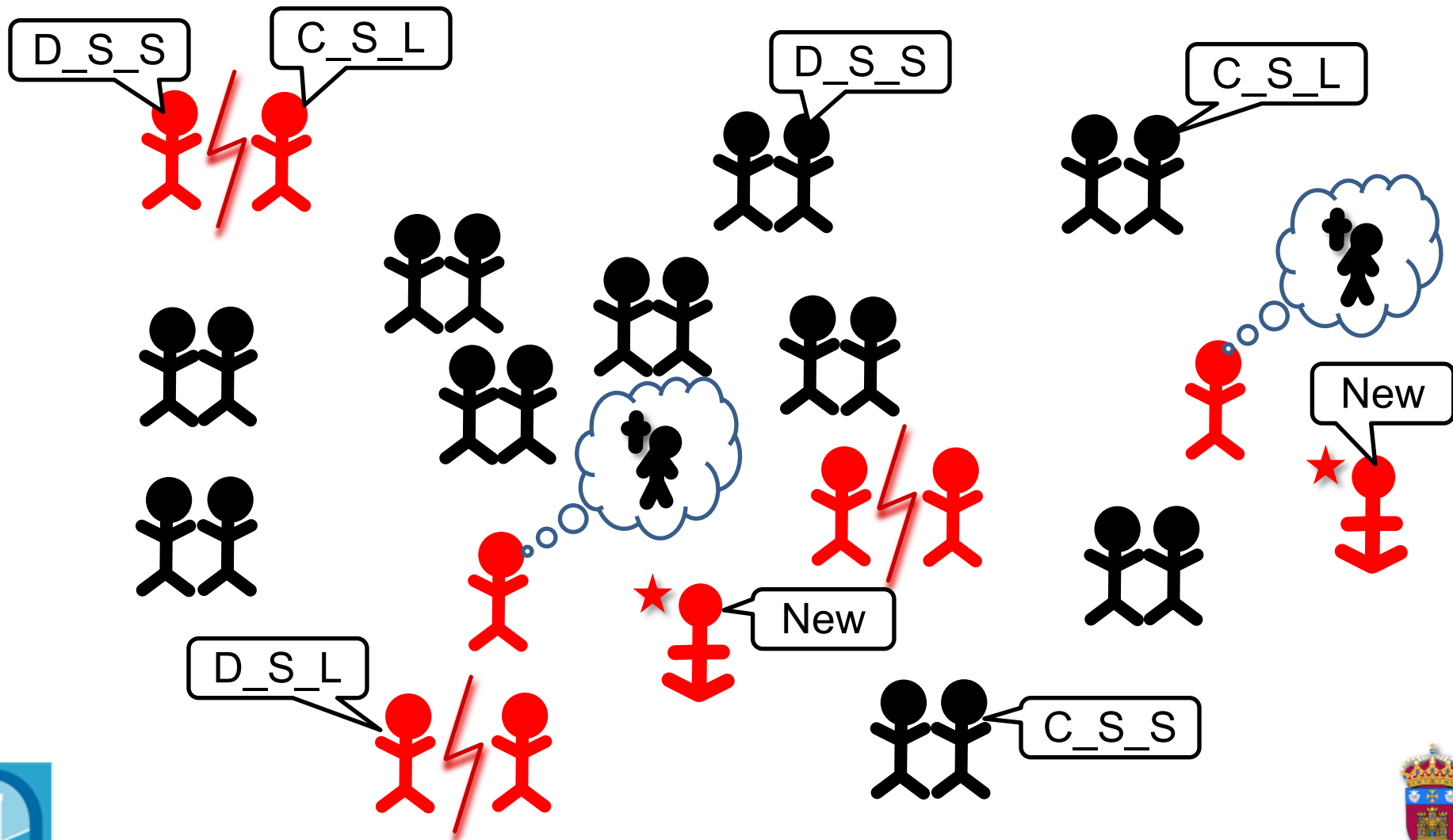
**Random mutations** occur with probability  $\mu$ .



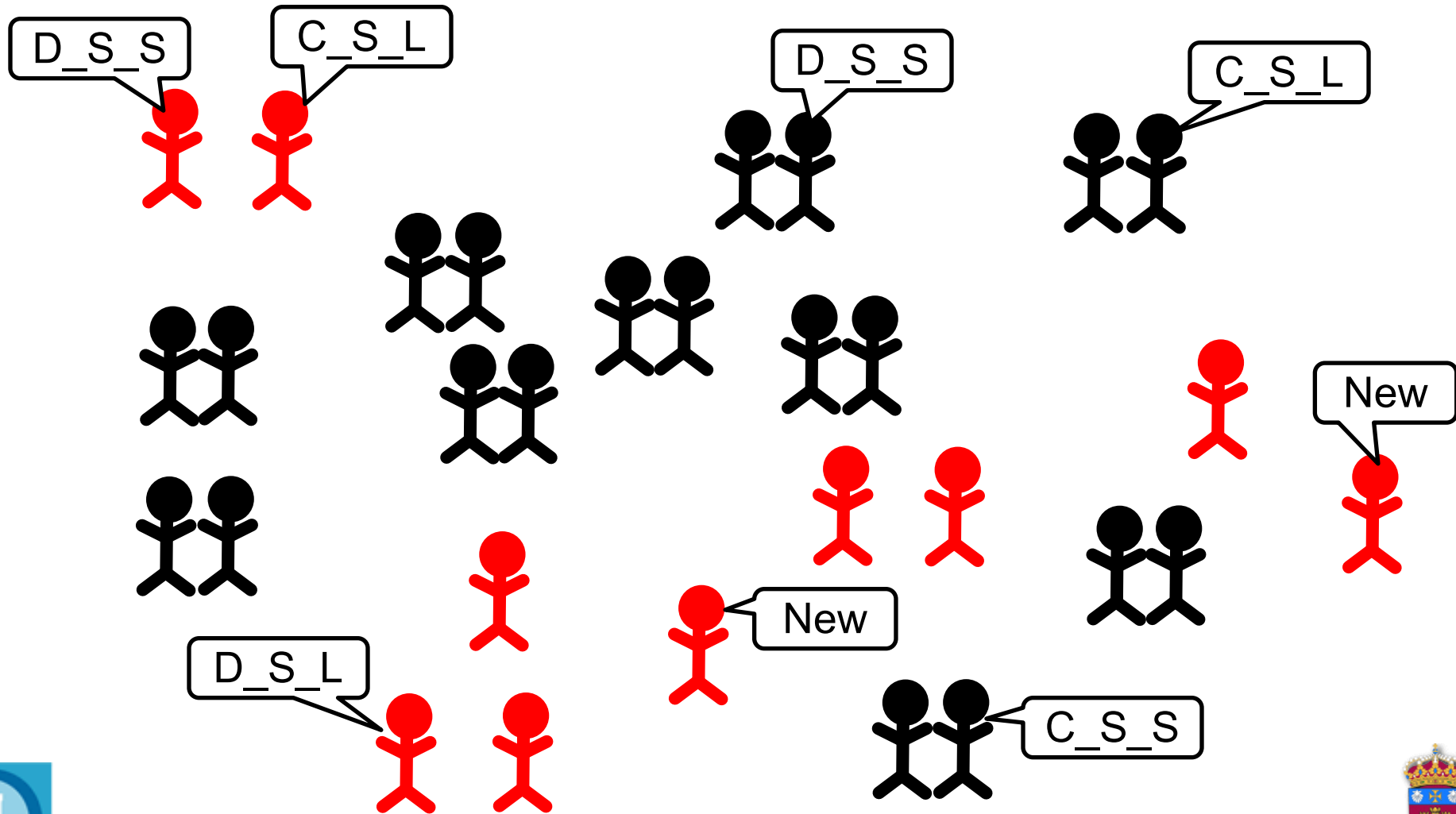
# The population for the next step



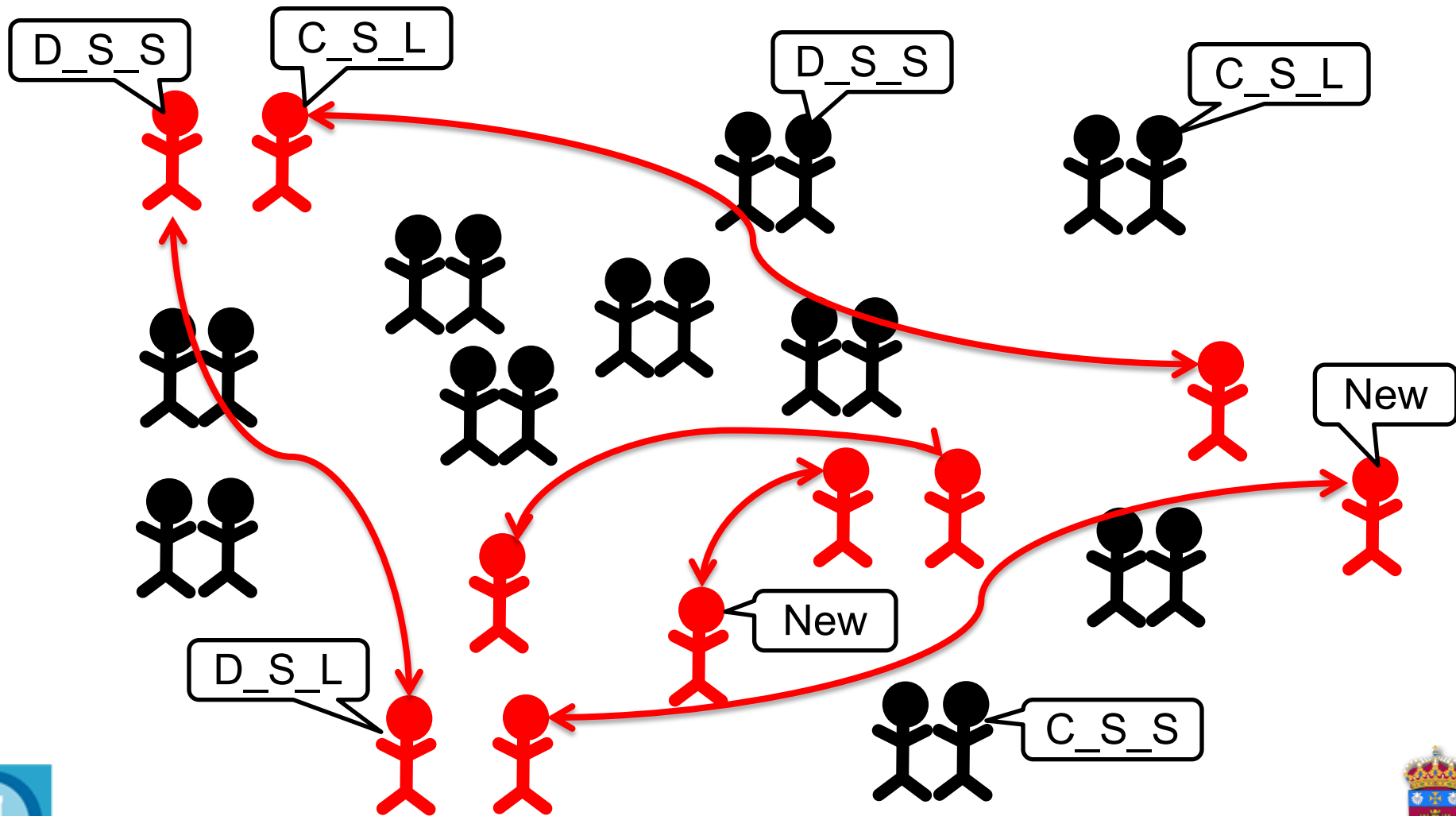
# The population for the next step



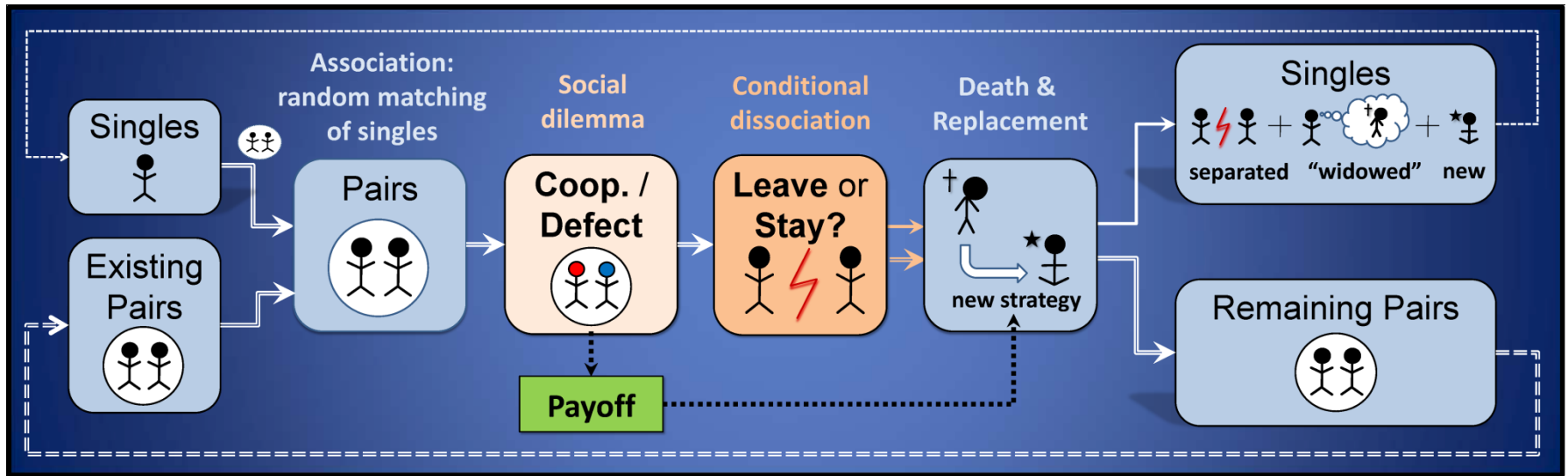
# The random pairing of singles



# The random pairing of singles



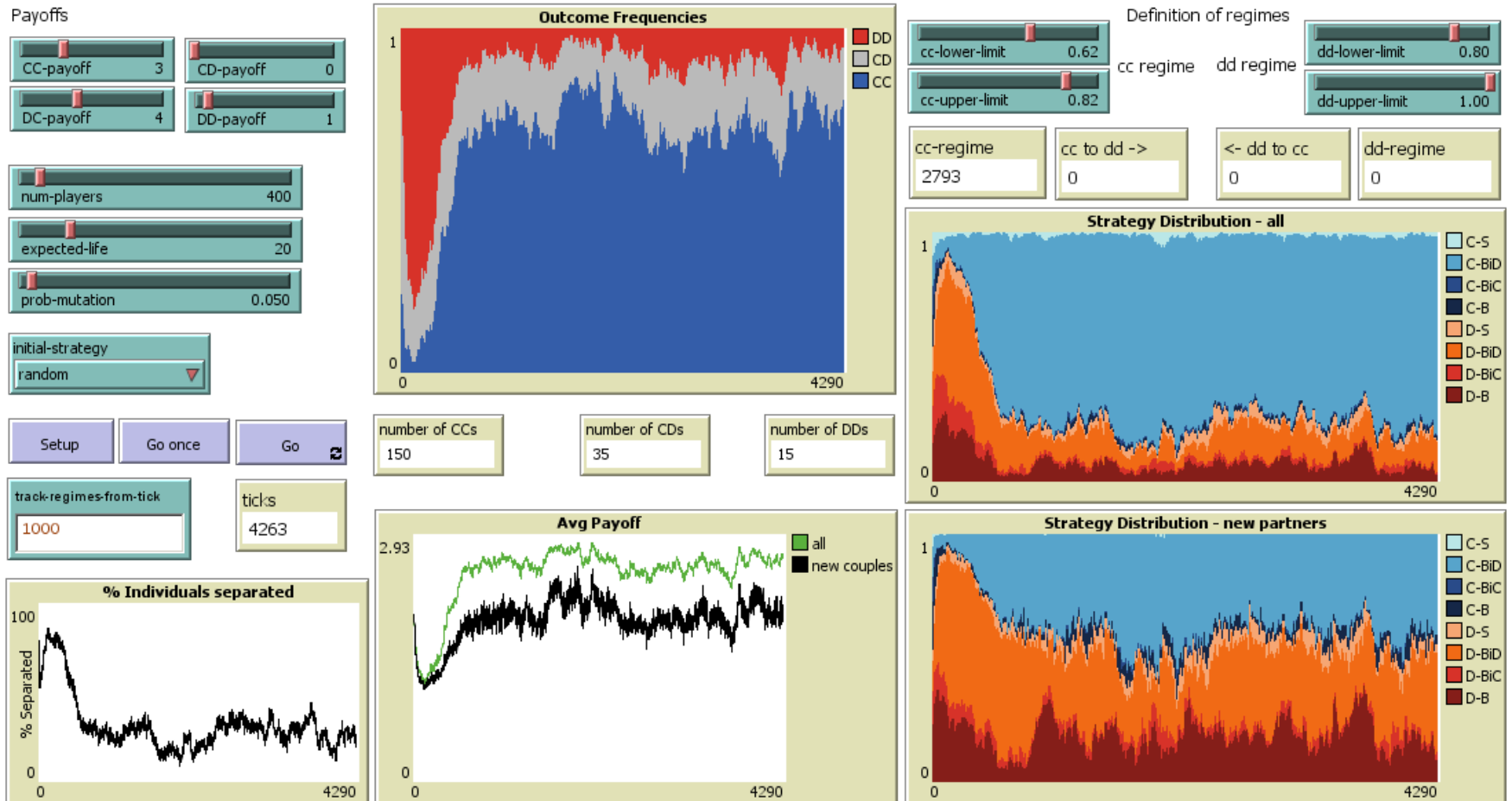
# The timeline



Sequence of events within each time period



# The implementation of the model



# Outline

---

- Introduction
- The question and the approach
- The model
- **Simulation results**
- **A mean-dynamics approximation**
- **A closed-form solution**
- **Conclusions**



# Three scenarios

---

## Key factor:

Expected lifespan of the individuals:

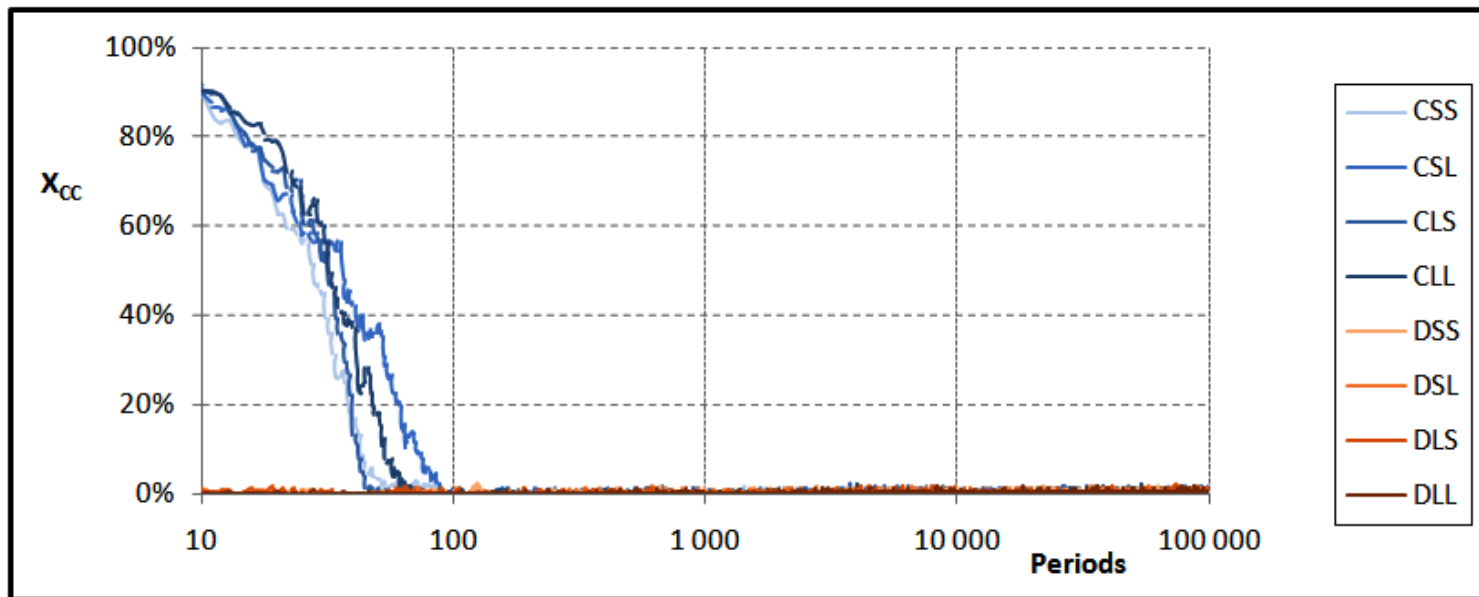
- Short life  $expLife = 5$
- Long life  $expLife = 50$
- Intermediate life  $expLife = 20$

Benchmark:  $N = 400$ ,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# Short life: non-cooperative regime

$x_{CC}$  : share of CC outcomes in a period



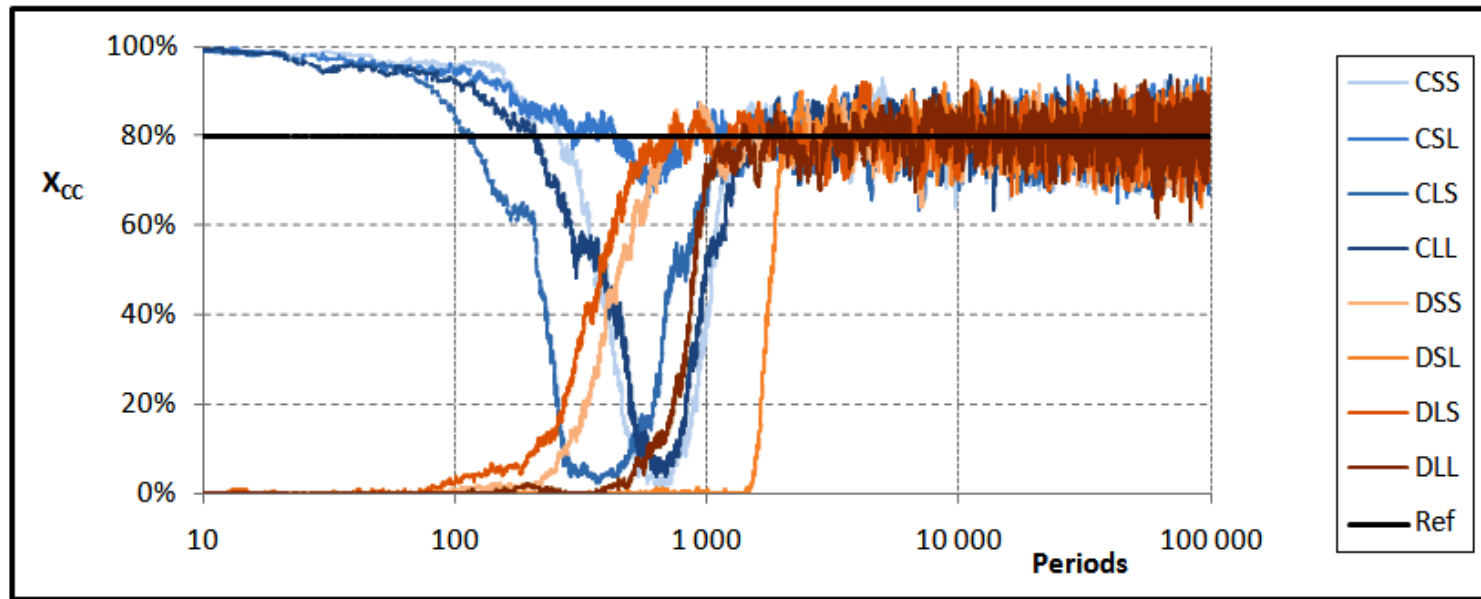
Evolution of the percentage of **CC outcomes** for 8 different runs, each run starting with the whole population using one of the 8 different strategies.

Parameterisation:  $N = 400$ ,  **$expLife = 5$** ,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# Long life: cooperative regime

$x_{CC}$  : share of CC outcomes in a period



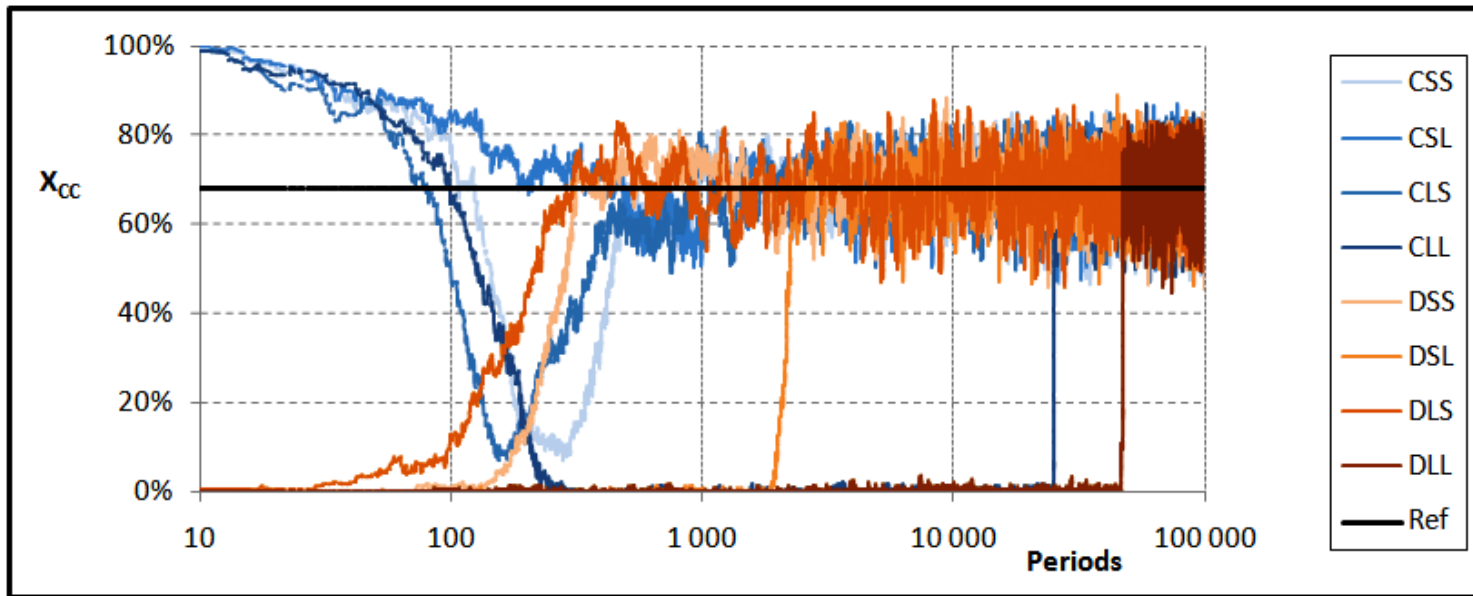
Evolution of the percentage of **CC outcomes** for 8 different runs, each run starting with the whole population using one of the 8 different strategies.

Parameterisation:  $N = 400$ ,  $\text{expLife} = 50$ ,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# Intermediate life: dd-reg $\leftrightarrow$ cc-reg

$x_{CC}$  : share of CC outcomes in a period



Evolution of the percentage of **CC outcomes** for 8 different runs, each run starting with the whole population using one of the 8 different strategies.

Parameterisation:  $N = 400$ , **expLife = 20**,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# The 2 regimes

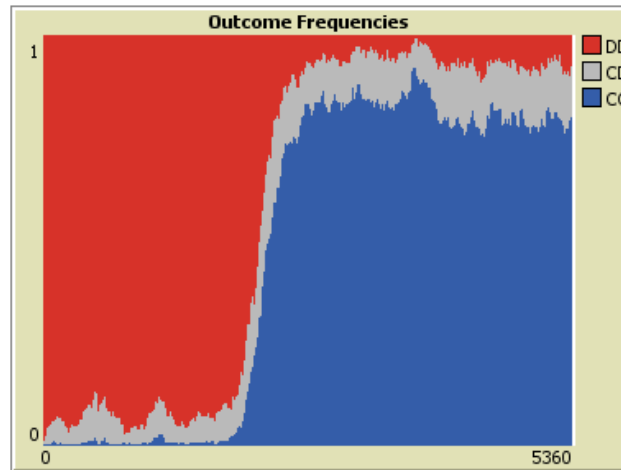
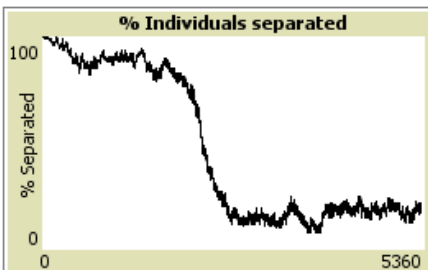
Payoffs



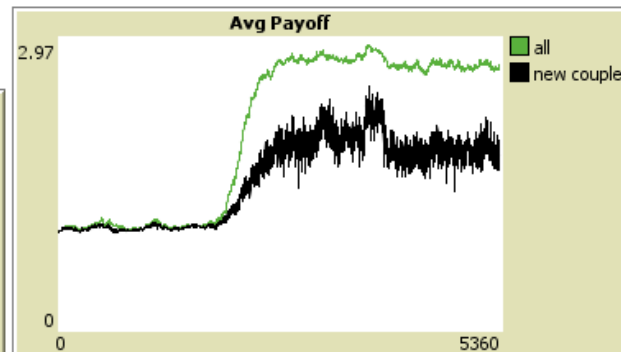
initial-strategy  
D-B

Setup    Go once    Go

track-regimes-from-tick: 1000  
ticks: 5324



number of CCs: 160  
number of CDs: 19  
number of DDs: 21

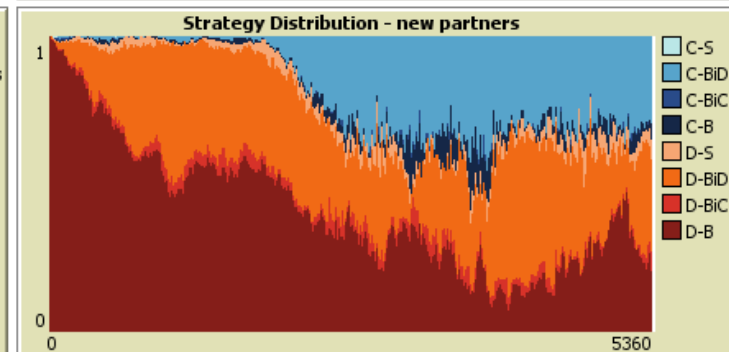
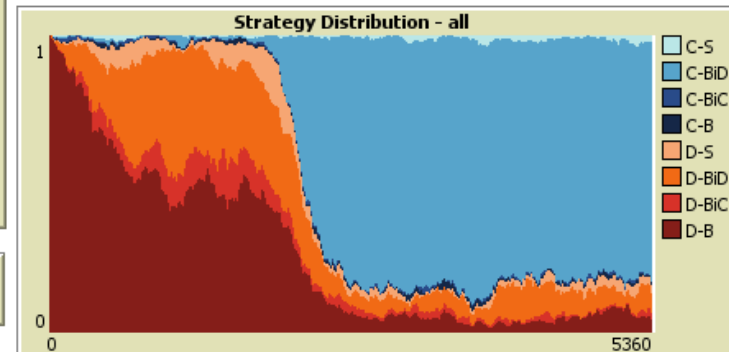


Definition of regimes

cc regime    dd regime

cc-lower-limit: 0.62    dd-lower-limit: 0.80  
cc-upper-limit: 0.82    dd-upper-limit: 1.00

cc-regime: 2269    cc to dd ->: 0    <- dd to cc: 1    dd-regime: 1032

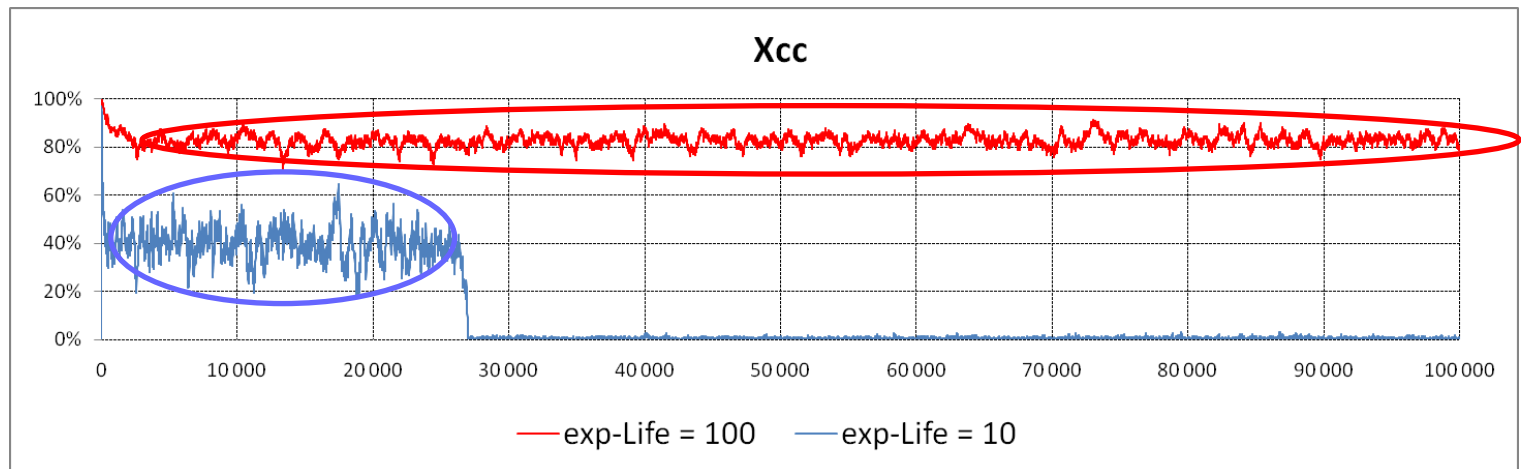


# Characterising the 2 regimes

- Non-cooperative regime... Easy:

$$x_{DD} \geq 0.8$$

- (partially) Cooperative regime... not trivial



Need to define a reference value:  $x_{CC}^{CR}(expLife)$

$x_{CC}$  : share of CC outcomes in a period



# Outline

---

- Introduction
- The question and the approach
- The model
- Simulation results
- **A mean-dynamics approximation**
- **A closed-form solution**
- **Conclusions**



# Mean-dynamics approximation

---

## Time-homogeneous Markov chain

Ergodic if  $expLife < \infty$  and  $\mu > 0$ .

Too many states, even for moderate values of  $N$ . (e.g.  $N=400 \rightarrow \#S = 6.53734 \times 10^{41}$ )

## Mean-dynamics approximation

When the population is very large, the law of large numbers enables us to:

- identify *ex ante* probabilities with *ex post* frequencies at the pairing stage,
- identify *expected* deaths with *average* deaths for each group of strategists,
- identify *ex ante* probabilities with *ex post* frequencies at the mutation stage.

This leads us to a deterministic set of 35 differential equations whose limiting behaviour may well depend on initial conditions.



# Mean-dynamics approximation

$$\frac{dp_{rq}(t)}{dt} = \phi_{rq} \delta^2 p_{rq}(t) + y_r(t) \frac{y_q(t)}{y(t)} - p_{rq}(t)$$

$$y_r = (1 - \delta) \left[ (1 - \mu) \frac{p_r \bar{\pi}_r}{\bar{\pi}} + \mu m_r \right] + \delta^2 \sum_{i \in \Lambda} (1 - \phi_{ri}) p_{ri} + \delta(1 - \delta) p_r$$

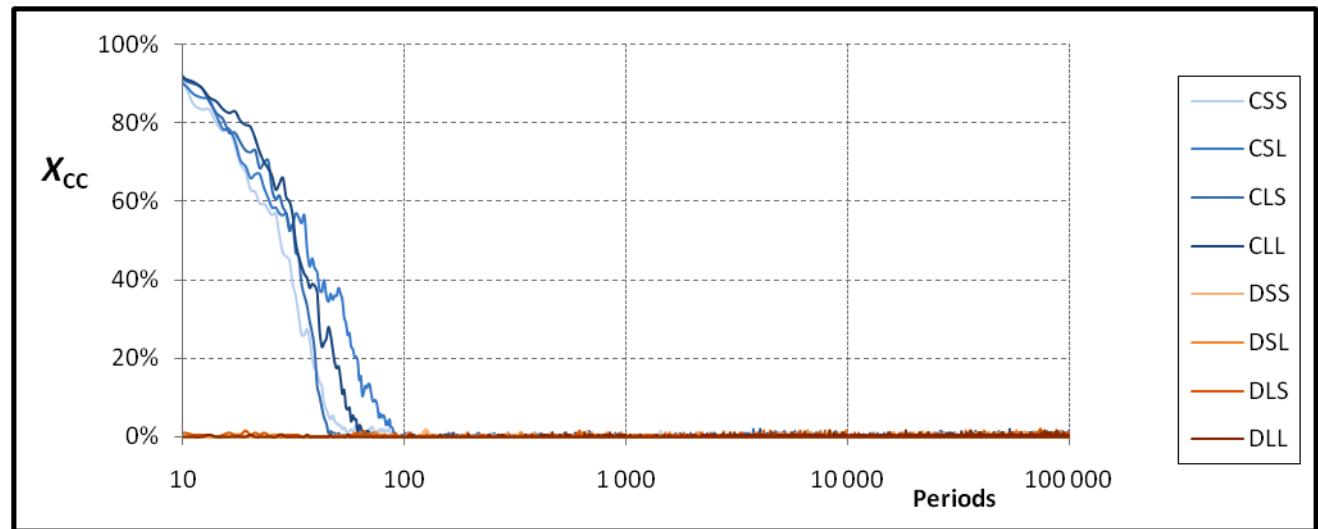
$$p_r = \sum_{i \in \Lambda} p_{ri} \quad \bar{\pi}(\mathbf{p}) = \sum_{i \in \Lambda} p_i \cdot \bar{\pi}_i(\mathbf{p})$$

$$\bar{\pi}_r(\mathbf{p}) = \begin{cases} \frac{1}{p_r} \left( R \sum_{i \in \Lambda_C} p_{ri} + S \sum_{i \in \Lambda_D} p_{ri} \right) & \text{if } r \in \Lambda_C \\ \frac{1}{p_r} \left( T \sum_{i \in \Lambda_C} p_{ri} + P \sum_{i \in \Lambda_D} p_{ri} \right) & \text{if } r \in \Lambda_D \end{cases}$$

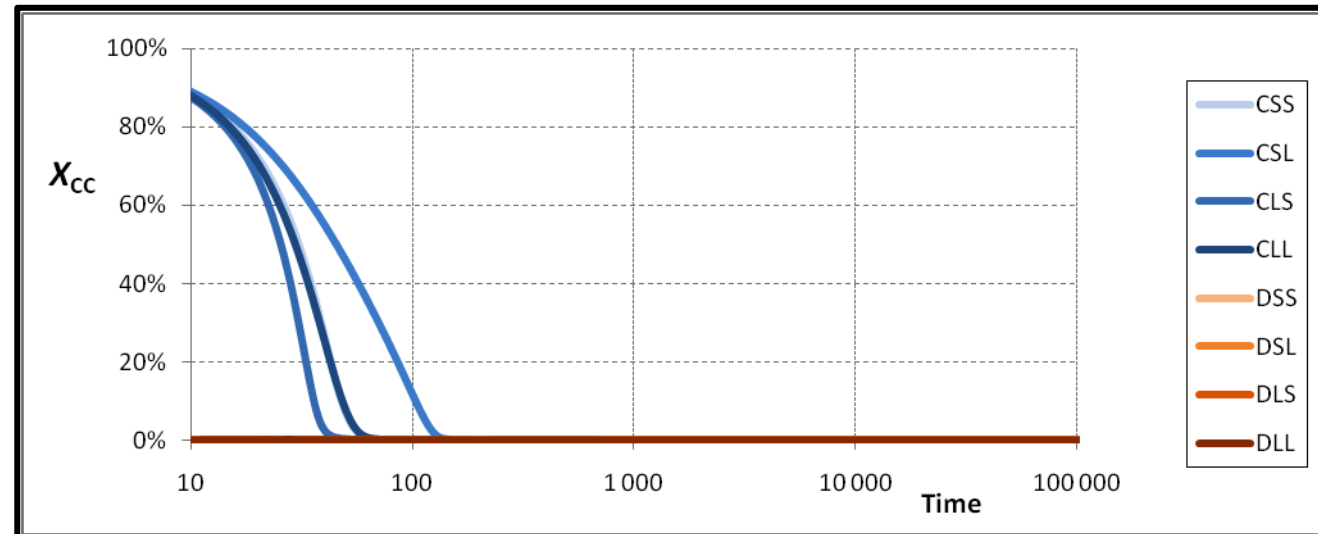


Evolution of the percentage of **CC outcomes** for 8 different runs, each run starting with the whole population using one of the 8 different strategies.  
Parameterisation:  $N = 400$ , **expLife = 5**,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .

Stochastic simulations

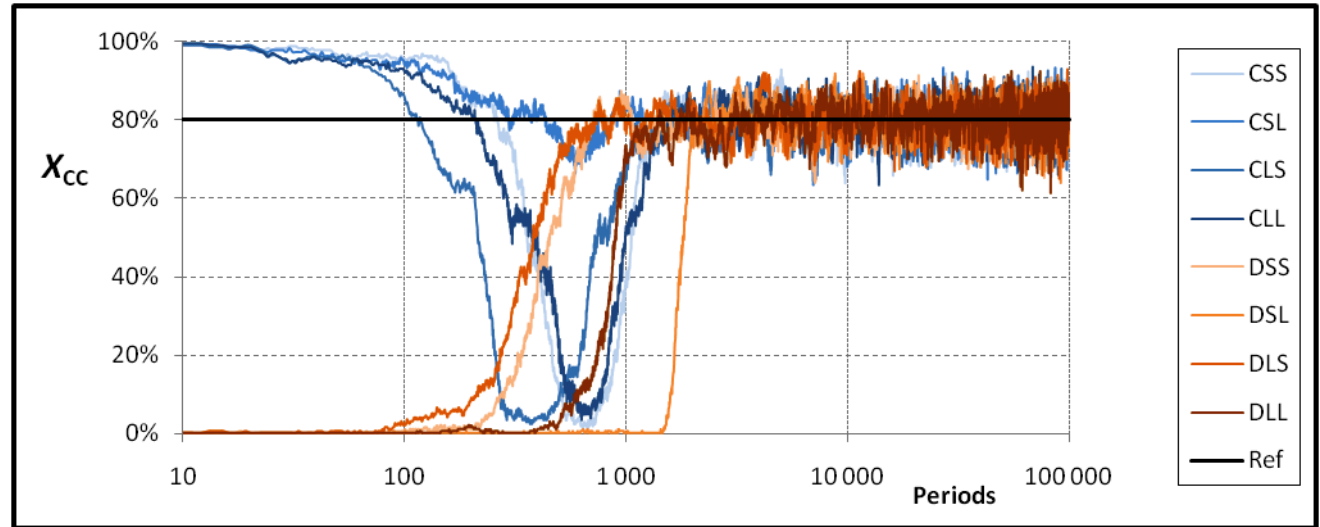


Mean-dynamics approximation

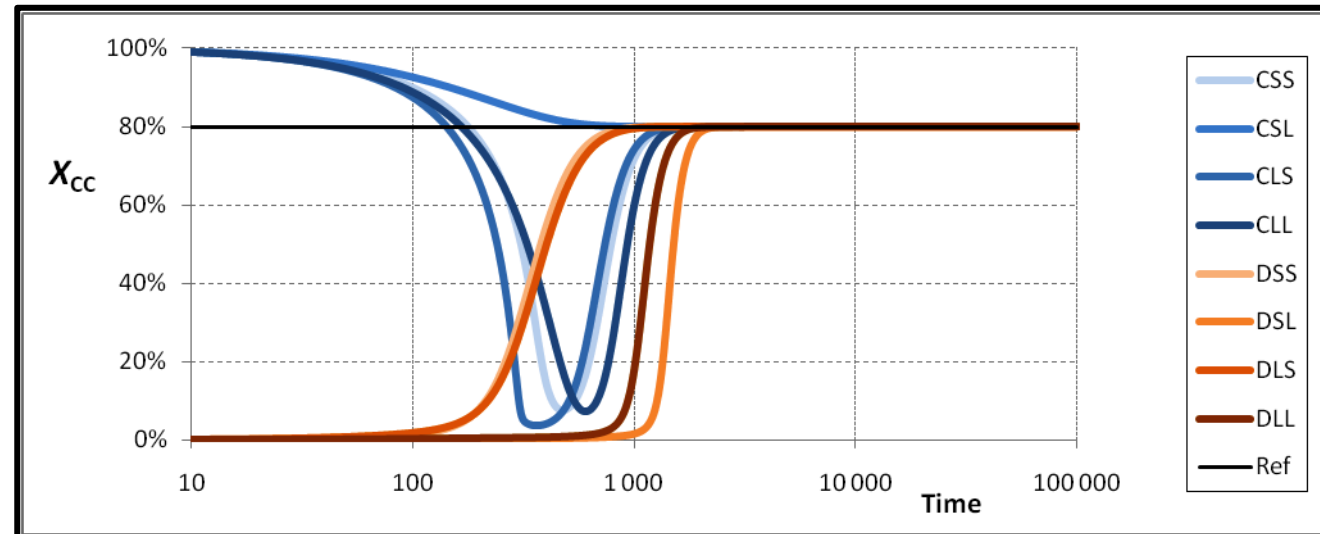


Evolution of the percentage of **CC outcomes** for 8 different runs, each run starting with the whole population using one of the 8 different strategies.  
Parameterisation:  $N = 400$ ,  $expLife = 50$ ,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .

Stochastic simulations

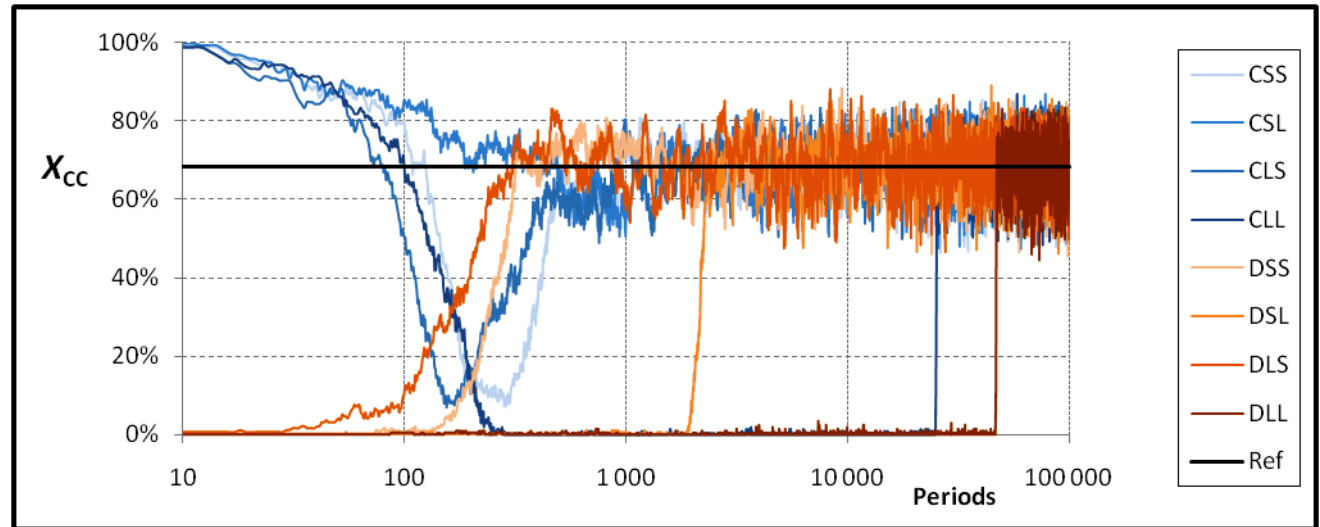


Mean-dynamics approximation

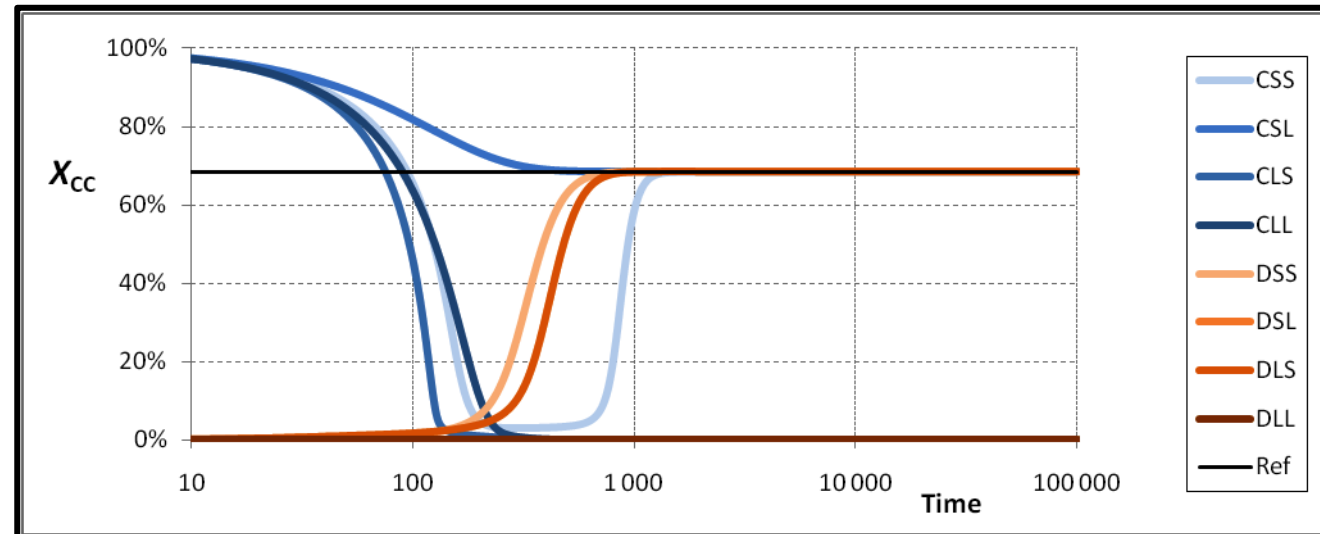


Evolution of the percentage of **CC outcomes** for 8 different runs, each run starting with the whole population using one of the 8 different strategies.  
 Parameterisation:  $N = 400$ , **expLife = 20**,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .

Stochastic simulations



Mean-dynamics approximation



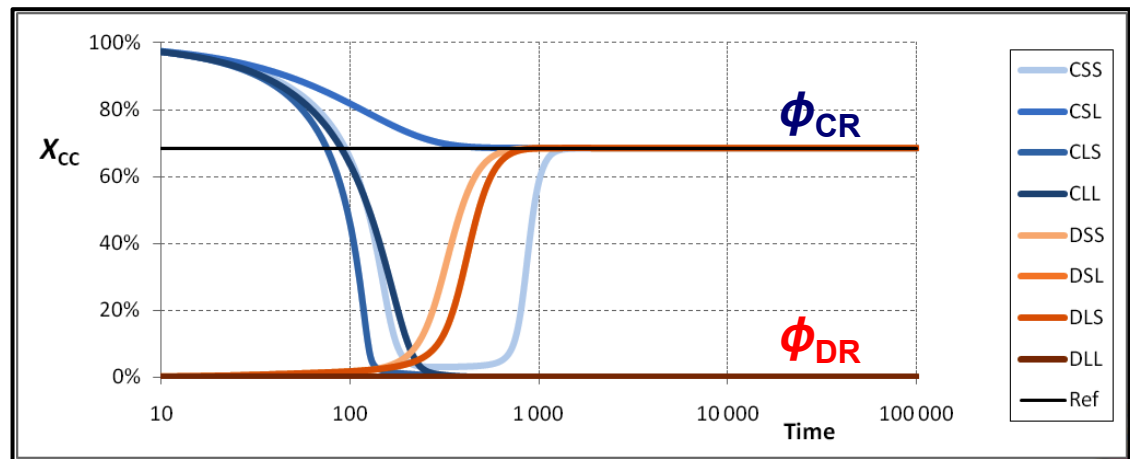
# Mean-Dynamics approximation

Numerical exploration of the mean-dynamics equations starting from different initial conditions, and for different values of **expLife** and small  $\mu > 0$  reveals:

- For expected life **expLife**  $< f_1$ , the MD equations converge to  $\phi_{DR}$ .
- For expected life  $f_1 \leq \mathbf{expLife} < f_2$  the MD equations converge either to  $\phi_{DR}$ , or to  $\phi_{CR}$ , characterised by high values of CC outcomes.
- For expected life  $f_2 \leq \mathbf{expLife}$  the MD equations converge to  $\phi_{CR}$ .

Example of initial conditions for which the MD equations converge to

- a) the cooperative attractor  $\phi_{CR}$ .
- b) the defective attractor  $\phi_{DR}$ .



# Mean-Dynamics approximation

Numerical exploration of the mean-dynamics equations starting from different initial conditions, and for different values of **expLife** and small  $\mu > 0$  reveals:

- For expected life **expLife**  $< f_1$ , the MD equations converge to  $\phi_{DR}$ .
- For expected life  $f_1 \leq \mathbf{expLife} < f_2$  the MD equations converge either to  $\phi_{DR}$ , or to  $\phi_{CR}$ , characterised by high values of CC outcomes.
- For expected life  $f_2 \leq \mathbf{expLife}$  the MD equations converge to  $\phi_{CR}$ .

We refer to the fraction of CC outcomes in  $\phi_{CR}$  as  $x_{CC}^{CR}$ . The longer the expected life, the greater the basin of attraction of  $\phi_{CR}$  and the higher the value of  $x_{CC}^{CR}$ . We use the value  $x_{CC}^{CR}$  to define the (partially) cooperative regime as:

$$\left| x_{CC} - x_{CC}^{CR} \right| \leq 0.1$$



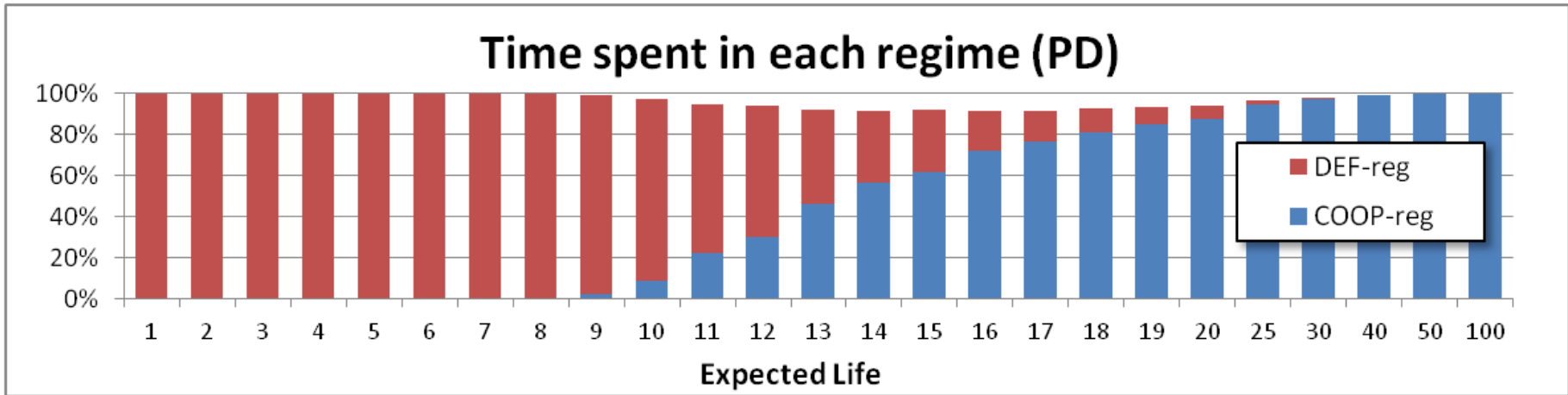
# Mean-Dynamics approximation

<i>expLife</i>	$x_{CC}^{CR}$	<i>Cooperative Regime</i>	<i>Non-Cooperative Regime</i>
8	-	-	$x_{DD} \geq 0.8$
9	33.16%	$0.2616 \leq x_{CC} \leq 0.4616$	
10	43.90%	$0.3390 \leq x_{CC} \leq 0.5390$	
15	61.57%	$0.5157 \leq x_{CC} \leq 0.6157$	
20	68.43%	$0.5843 \leq x_{CC} \leq 0.7843$	
25	72.30%	$0.6230 \leq x_{CC} \leq 0.8230$	
30	74.85%	$0.6485 \leq x_{CC} \leq 0.8485$	
40	78.04%	$0.6804 \leq x_{CC} \leq 0.8804$	
50	80.00%	$0.7000 \leq x_{CC} \leq 0.9000$	
100	84.24%	$0.7424 \leq x_{CC} \leq 0.9424$	

Parameterisation:  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# Results

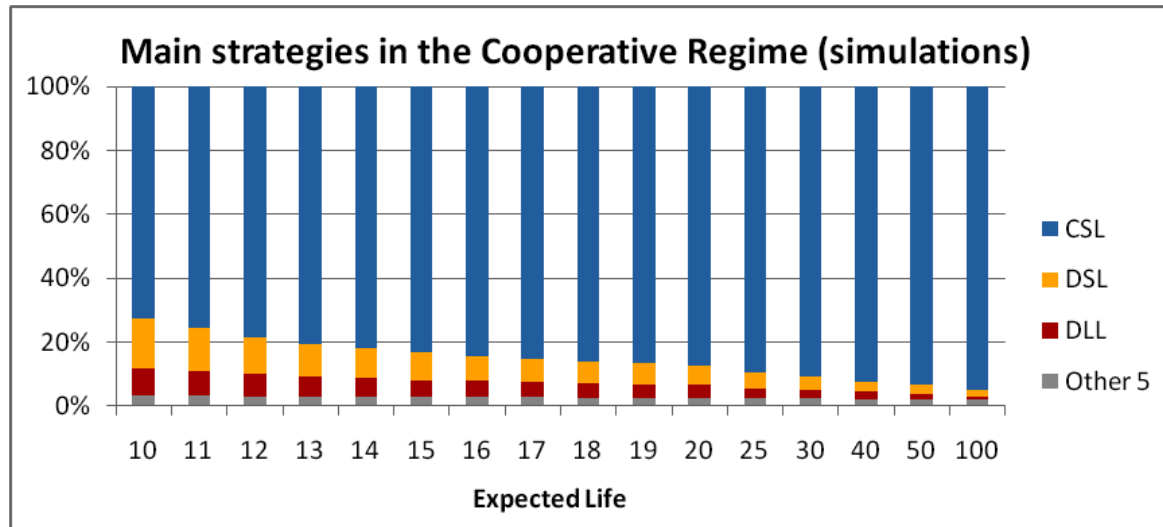


Fraction of periods spent in **the non-cooperative** and in **the cooperative** regimes as a function of the expected life *expLife*.

The values in each column are compiled over  $10^3$  simulation runs. Every run measured between periods  $3 \cdot 10^3$  and  $10^4$ , with random initial conditions. Parameterisation:  $N = 400$ ,  $\mu = 0.05$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



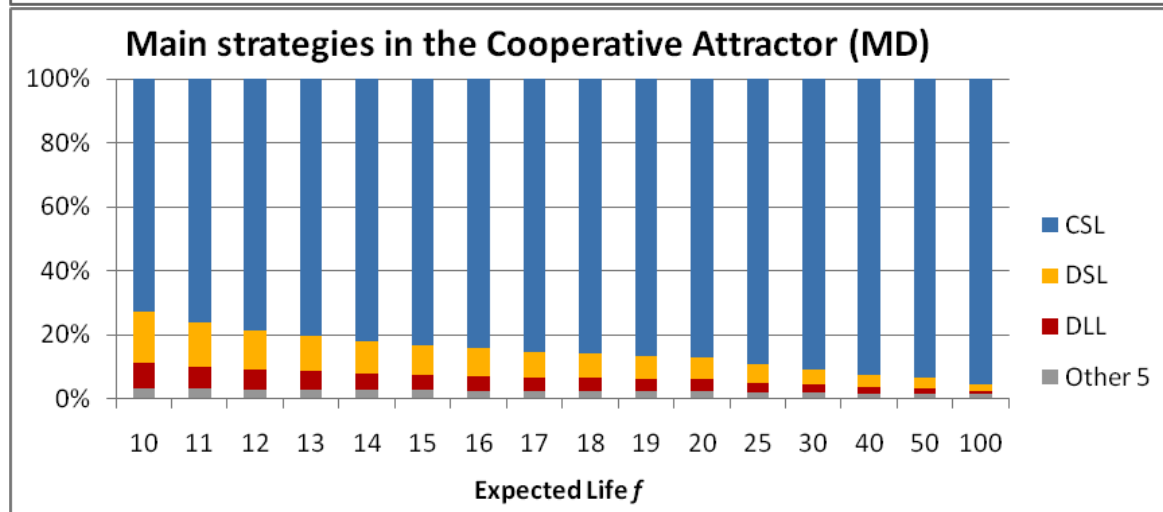
# Distribution of Strategies in the cooperative regime



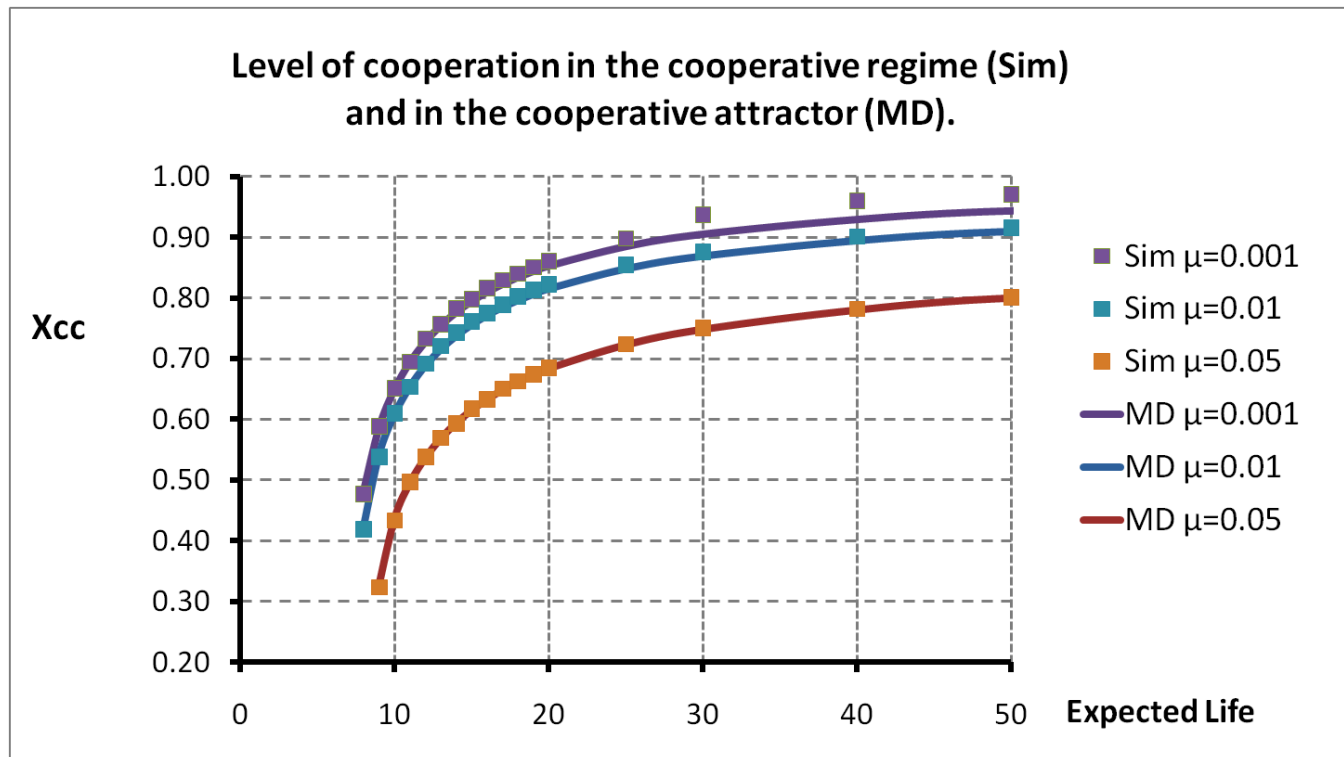
The values in each column are compiled over 1000 simulation runs.

Every run measured between periods  $3 \cdot 10^3$  and  $10^4$ , with random initial conditions.

Parameterisation:  
 $N = 400$ ,  $\mu = 0.01$ ,  
 $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# Level of cooperation



Average values of the level of cooperation ( $x_{CC}$ ) in the cooperative regime (stochastic simulations) and in the cooperative attractor (Mean Dynamics) as a function of the individuals' expected life  $expLife$ , for different values of  $\mu$ .

Parameterisation:  $N = 400$ ,  $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# Outline

---

- Introduction
- The question and the approach
- The model
- Simulation results
- A mean-dynamics approximation
- **A closed-form solution**
- **Conclusions**



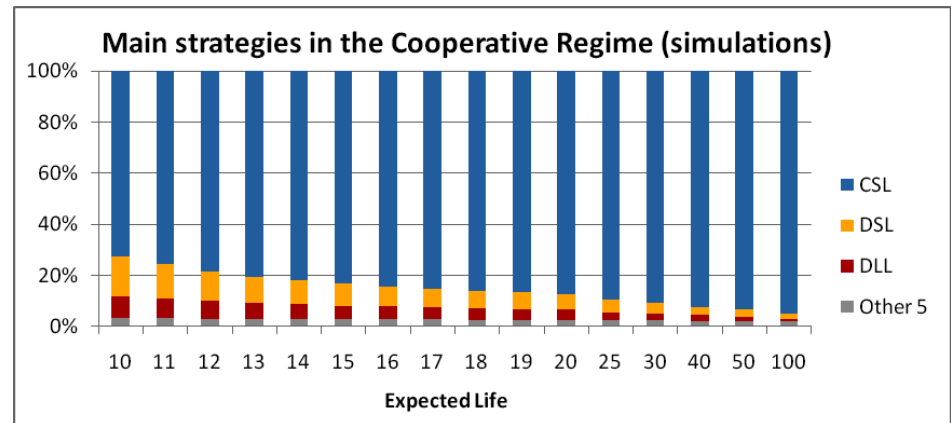
# Reduced mean-dynamics approximation

Reduced mean-dynamics approximation to try to derive a closed-form solution for the level of cooperation in the cooperative regime for arbitrary payoffs and arbitrary mutation.

$$x_{CC}^{CR}(expLife, T, R, P, S)$$

Focus only on the strategies that the numerical simulations single out as the most prevalent in the cooperative regime:

**CSL** , **DSL** and **DLL**.



Also, these strategies are the only ones that can be part of a (partially) cooperative Nash equilibrium (appropriately defined for this dynamic context).



# Reduced mean-dynamics approximation

$$\dot{x}_{CC} = \frac{y_C^2}{y} + (1-\beta)^2 x_{CC} - x_{CC}$$

$$y = 1 - (1-\beta)^2 x_{CC}$$

$$\dot{x}_{DD} = \frac{y_D^2}{y} - x_{DD}$$

$$y_C = \beta \left[ (1-\mu) \frac{\pi_C}{\pi_C + \pi_D} + \frac{\mu}{4} \right] + (1-\beta) \left( \beta x_{CC} + \frac{x_{CD}}{2} \right)$$

$$\dot{x}_{CD} = 2 \frac{y_C y_D}{y} - x_{CD}$$

$$y_D = \beta \left[ (1-\mu) \frac{\pi_D}{\pi_C + \pi_D} + \frac{3\mu}{4} \right] + (1-\beta) \left( x_{DD} + \frac{x_{CD}}{2} \right)$$

**Only 3 state variables  
(type of interaction)  
that add up to one.**

$$\pi_C = R x_{CC} + S \frac{x_{CD}}{2}$$

$$\pi_D = P x_{DD} + T \frac{x_{CD}}{2}$$

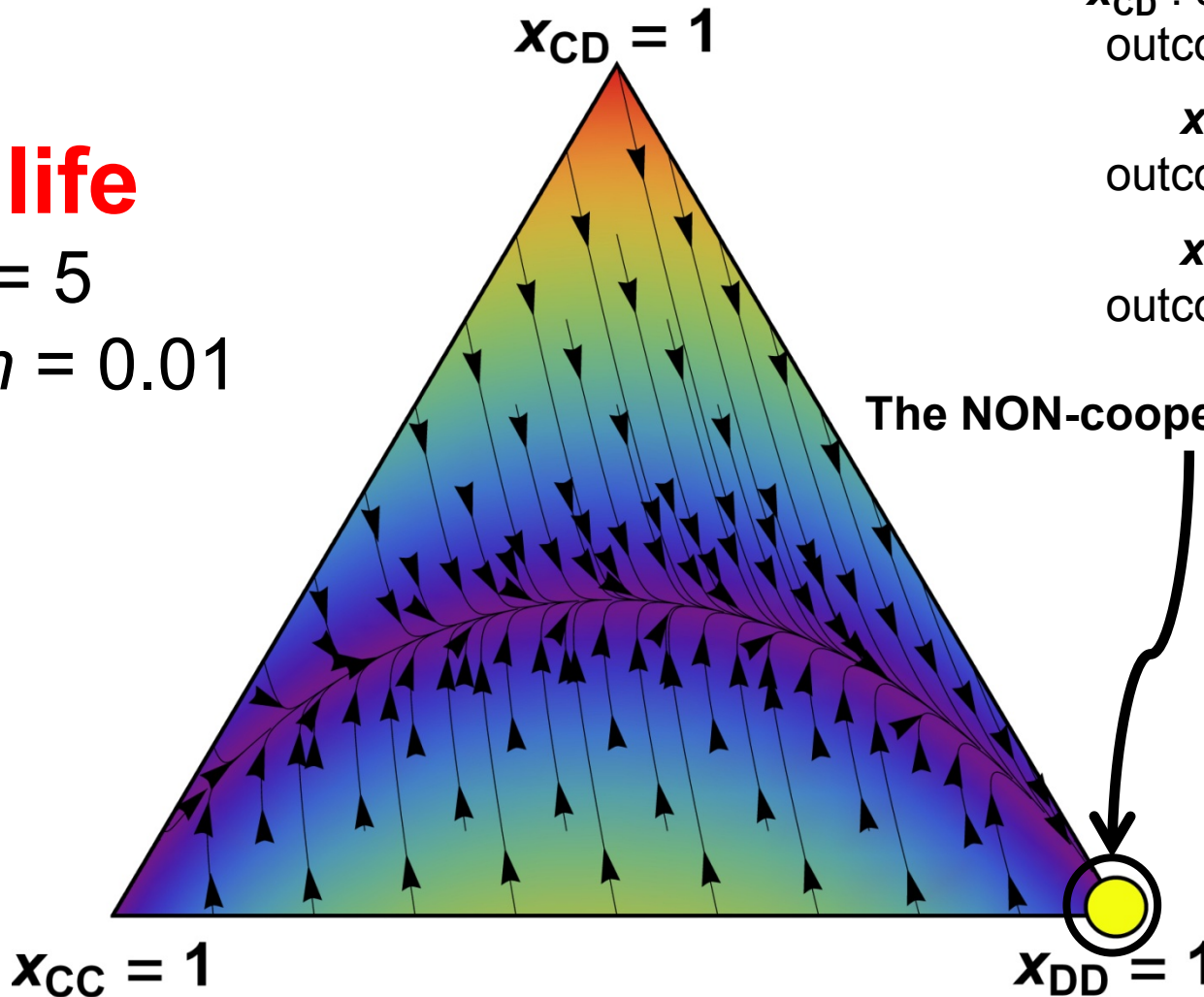


# Reduced mean-dynamics approximation

**Short life**

*expLife* = 5

*Mutation* = 0.01



$x_{CD}$  : share of CD, DC outcomes in a period

$x_{CC}$  : share of CC outcomes in a period

$x_{DD}$  : share of DD outcomes in a period



# Reduced mean-dynamics approximation

## Moderate life

$expLife = 20$

$Mutation = 0.01$

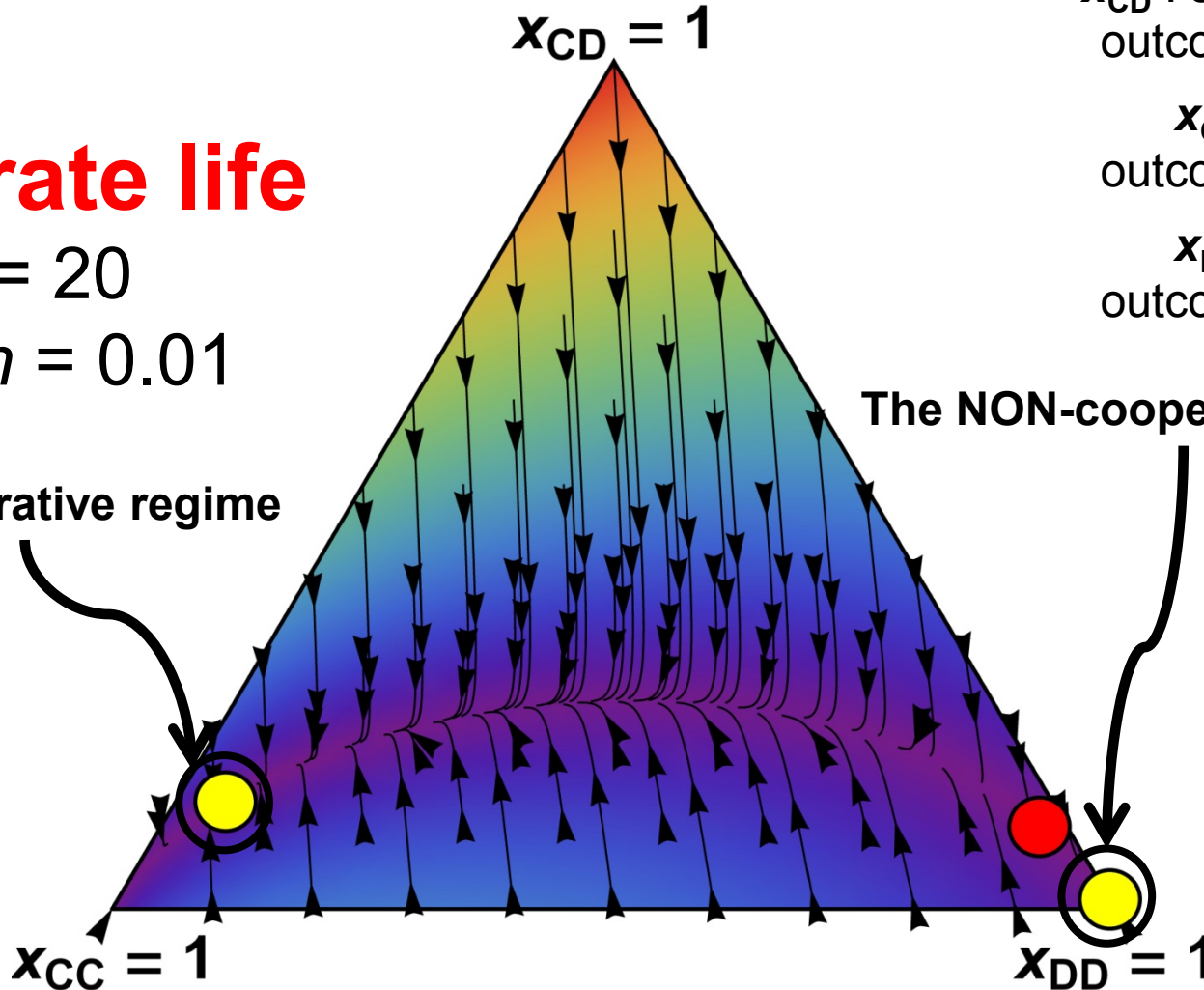
$x_{CD}$  : share of CD, DC outcomes in a period

$x_{CC}$  : share of CC outcomes in a period

$x_{DD}$  : share of DD outcomes in a period

The cooperative regime

The NON-cooperative regime



# Reduced mean-dynamics approximation

**Longer life**

$expLife = 50$

$Mutation = 0.01$

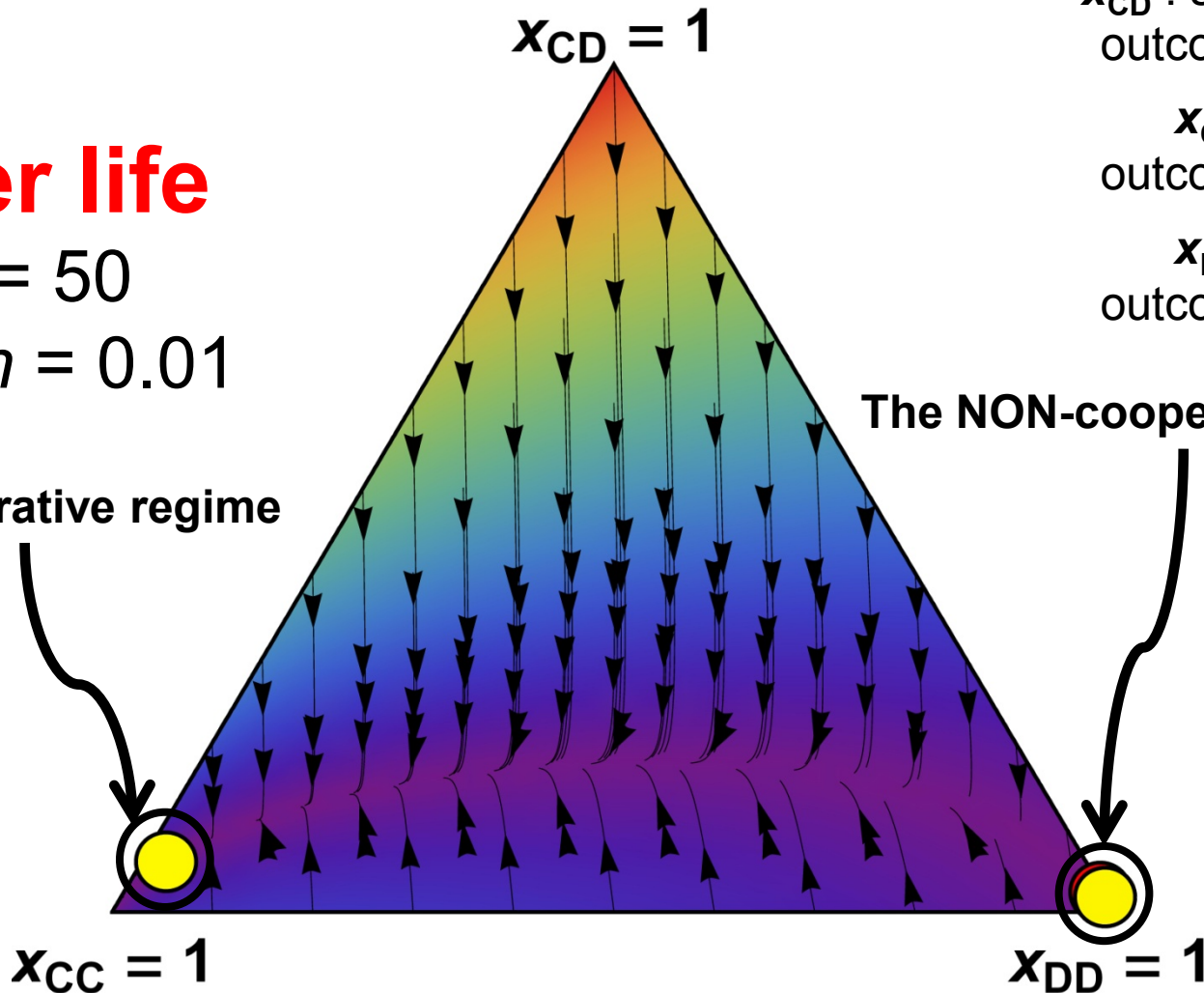
$x_{CD}$  : share of CD, DC  
outcomes in a period

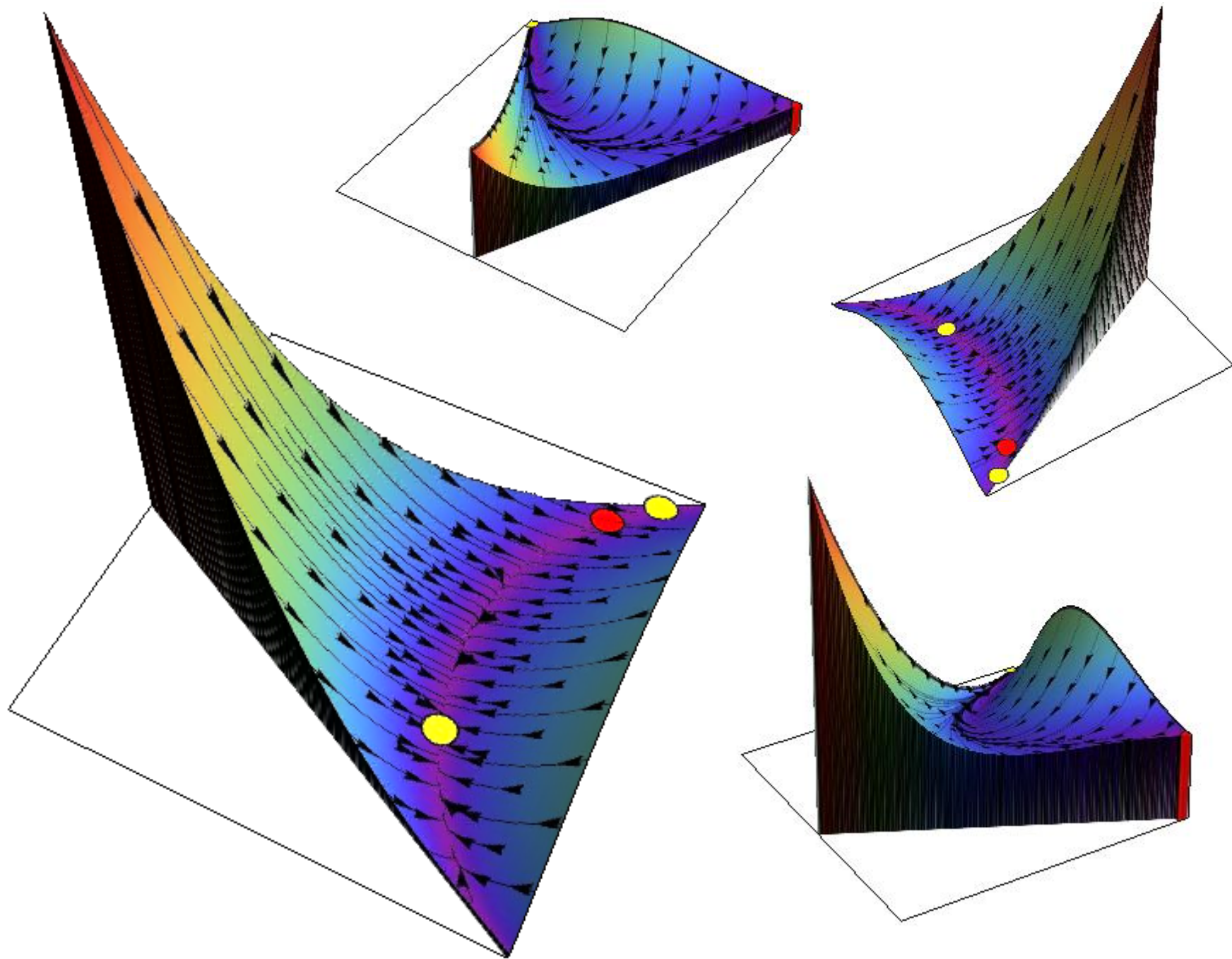
$x_{CC}$  : share of CC  
outcomes in a period

$x_{DD}$  : share of DD  
outcomes in a period

The cooperative regime

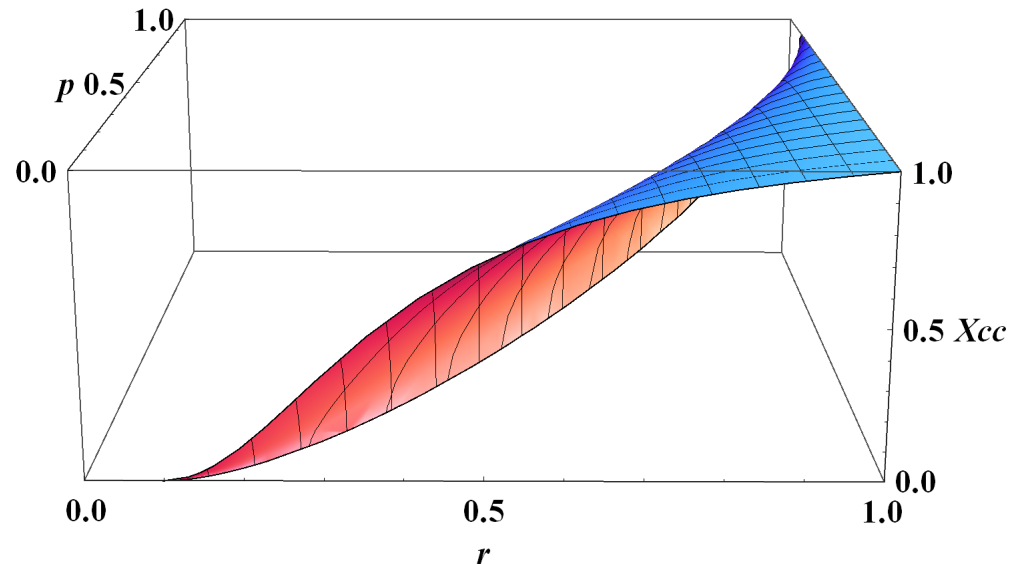
The NON-cooperative regime





# Reduced mean-dynamics approximation

$$x_{CC}^* = \frac{m^2 + \delta(1 - 2p)(\delta - 2(1 - r)) + |m - \delta(1 - 2p)|\sqrt{(m - \delta)^2 - 4rp\delta}}{2\delta(m^2(1 - \delta) + \delta(r - p)^2)}$$



where

$$\delta = \left(1 - \frac{1}{\text{expLife}}\right)^2$$

$$m \equiv 1 - r - p$$

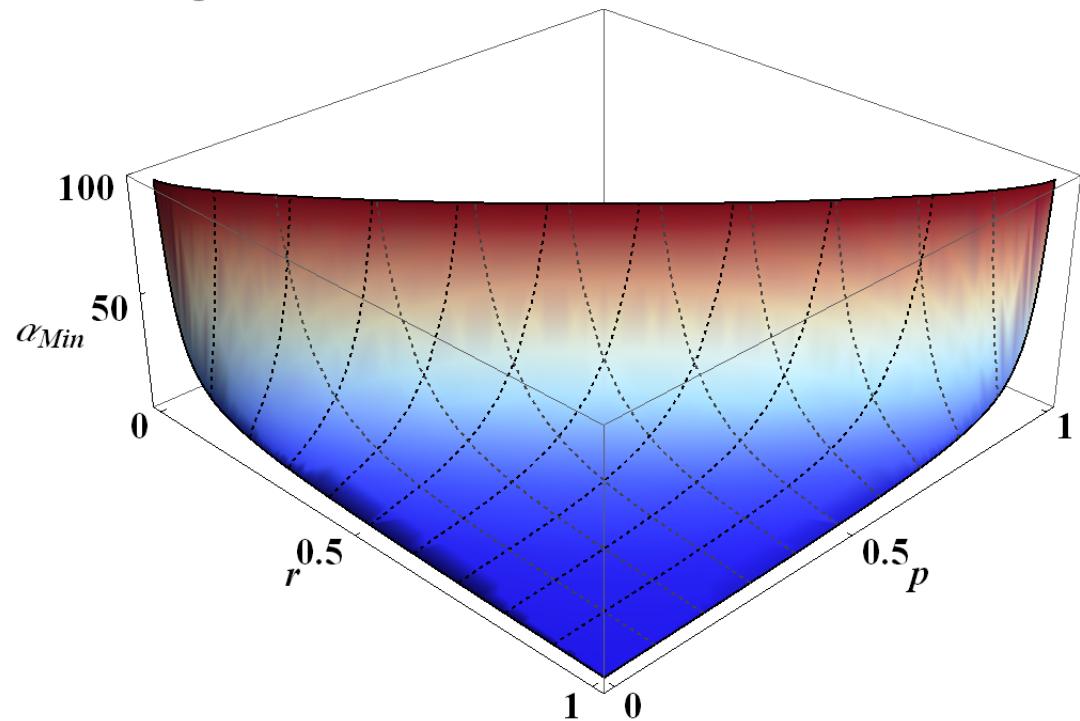
$$0 < p = \frac{P - S}{T - S} < r = \frac{R - S}{T - S} < 1$$

(No mutation)



# Reduced mean-dynamics approximation

$$\text{expLife}_{\text{Min}} = \frac{1}{1 - \sqrt{rp} - \sqrt{(1-r)(1-p)}}$$

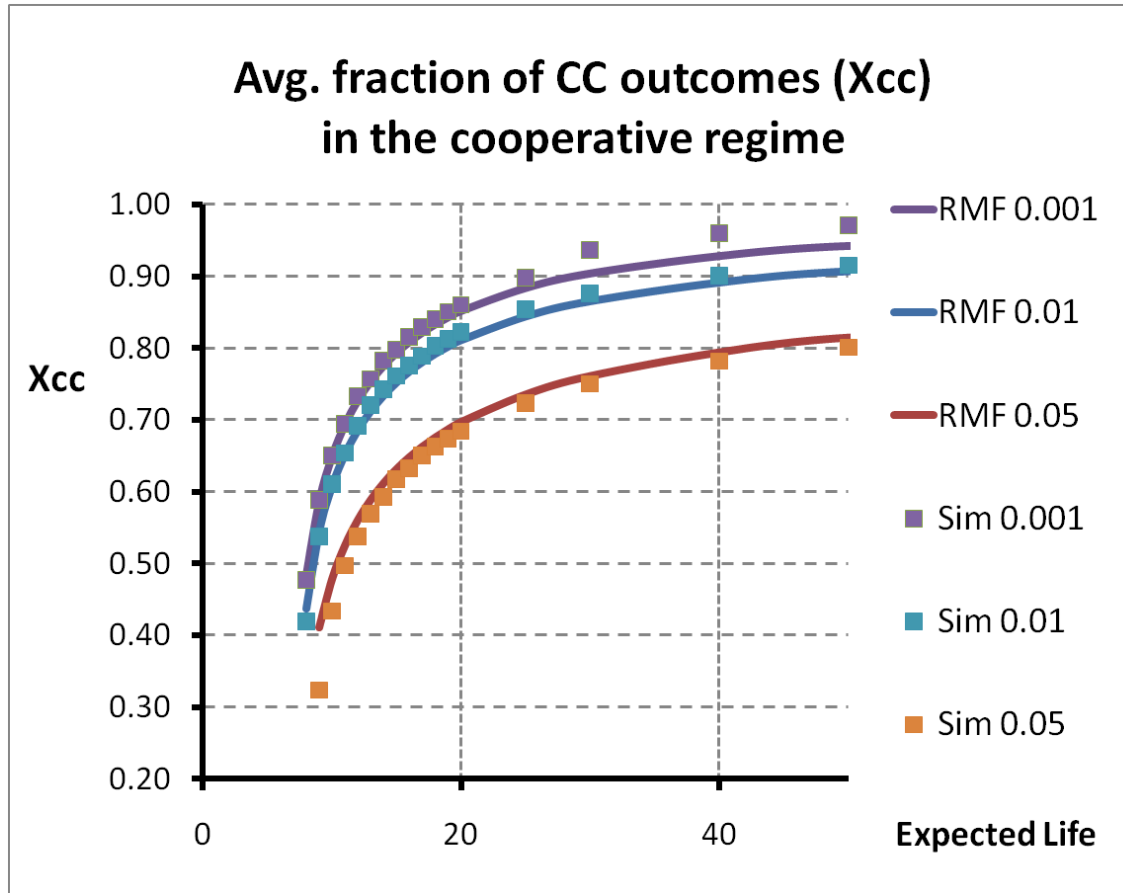


where  $0 < p = \frac{P-S}{T-S} < r = \frac{R-S}{T-S} < 1$

(No mutation)



# Reduced mean-dynamics approximation



Average values of the level of cooperation ( $x_{CC}$ ) in the cooperative regime as a function of the individuals' expected life  $expLife$ , both in the reduced mean-dynamics approximation and in the stochastic simulations with different values of  $\mu$ .

Parameterisation:  $N = 400$ ,  
 $T = 4$ ,  $R = 3$ ,  $P = 1$ ,  $S = 0$ .



# Outline

---

- Introduction
- The question and the approach
- The model
- Simulation results
- A mean-dynamics approximation
- A closed-form solution
- **Conclusions**



# Conclusions

---

- A simple mechanism of conditional dissociation can explain the evolutionary emergence of cooperation.
- Key factor: expected lifespan of the individuals. It is sufficient that lifespans are only moderately long.
- Cooperative regime mostly composed of “*conditional dissociators*”, *i.e.* cooperators that respond to defection by leaving.
- We have been able to derive a closed-form solution for arbitrary payoffs.





# Leaving undesirable partners

*- A sufficient condition to explain the evolutionary emergence of cooperation*

**Luis R. Izquierdo**

University of Burgos (Spain)

**Segismundo S. Izquierdo**

University of Valladolid (Spain)

**Fernando Vega-Redondo**

European University Institute (Italy)

Paper: <http://dx.doi.org/10.1016/j.jedc.2014.06.007>

Online model: <http://luis.izqui.org/models/LeLeLe/index.html>

5-minute video: [http://luis.izqui.org/papers/Izquierdo\\_Izquierdo\\_Vega-Redondo\\_2014.html](http://luis.izqui.org/papers/Izquierdo_Izquierdo_Vega-Redondo_2014.html)